

Scalar Curvature of C-totally Real Submanifolds in Sasakian Space Forms

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Abstract

We establish a sharp inequality between the squared mean curvature and the scalar curvature for a C-totally real submanifold of maximum dimension in a Sasakian space form. The equality case is investigated.

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Key words: Sasakian space form, Riemannian manifold, sectional curvature.

§1. Introduction

Let M be an n -dimensional Riemannian manifold. Denote by $K(\pi)$ the sectional curvature of the plane section $\pi \subset T_p M$, $p \in M$. For any orthonormal basis $\{e_1, \dots, e_n\}$ of the tangent space $T_p M$, the *scalar curvature* τ at p is defined by

$$\tau = \sum_{1 \leq i < j \leq n} K(e_i \wedge e_j).$$

If M is a submanifold of a Riemannian manifold \widetilde{M} and $p \in M$ and $\{e_1, \dots, e_n\}$ is an orthonormal basis of the tangent space $T_p M$, we denote by H the *mean curvature vector*, that is

$$H(p) = \frac{1}{n} \sum_{i=1}^n h(e_i, e_i)$$

Also, we set

$$h_{ij}^r = g(h(e_i, e_j), e_r)$$
$$\|h\|^2 = \sum_{i,j=1}^n g(h(e_i, e_j), h(e_i, e_j))$$

Here, we review briefly some known facts on *Jacobi's elliptic functions* for later use ([2]).

Put

$$(1) \quad u = \int_0^x \frac{dt}{\sqrt{(1-t^2)(1-k^2t^2)}},$$

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$$K = \int_0^1 \frac{dt}{\sqrt{(1-t^2)(1-k^2t^2)}},$$

where we first suppose that x and k satisfy $0 < k < 1$, $-1 \leq x \leq 1$. Equation (1) defines u as an odd function of x which is positive, increasing from 0 to K as x increases from 0 to 1. Inversely, the same equation defines x as an odd function of u which increases from 0 to 1 as u increases from 0 to K ; this function is known as a Jacobi's elliptic function, denoted by $sn(u, k)$ (or simply by $sn(u)$), so that we can put

$$u = sn^{-1}(x), \quad x = sn(u).$$

The other two main Jacobi's functions $cn(u, k)$ and $dn(u, k)$ (simply denoted respectively by $cn(u)$ and $dn(u)$) are defined by

$$cn(u) = \sqrt{1 - sn^2(u)}, \quad dn(u) = \sqrt{1 - k^2 sn^2(u)},$$

the square roots are positive so long as u is confined to the interval $-K < u < K$, so that $cn(u)$ and $dn(u)$ are even functions of u . Let $k' = \sqrt{1 - k^2}$ be the complementary modulus. Then $dn(u) \geq k' > 0$.

§3. Submanifolds of a Sasakian space form

Let (\tilde{M}, g) be a $(2m + 1)$ -dimensional Riemannian manifold endowed with an endomorphism φ ($(1, 1)$ -tensor field) of its tangent bundle $T\tilde{M}$, a vector field ξ and a 1-form η such that

$$\begin{cases} \varphi^2 X = -X + \eta(X)\xi, & \varphi\xi = 0, \quad \eta \circ \varphi = 0, \quad \eta(\xi) = 1, \\ g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y), & \eta(X) = g(X, \xi), \end{cases}$$

for all vector fields $X, Y \in \Gamma(T\tilde{M})$.

If, in addition, $d\eta(X, Y) = g(\varphi X, Y)$, then \tilde{M} is said to have a *contact Riemannian structure* (φ, ξ, η, g) . If, moreover, the structure is normal, i.e. if $[\varphi X, \varphi Y] + \varphi^2[X, Y] - \varphi[X, \varphi Y] - \varphi[\varphi X, Y] = -2d\eta(X, Y)\xi$, then the contact Riemannian structure is called a *Sasakian structure* and \tilde{M} is called a *Sasakian manifold*. For more details and background, we refer to the standard references [2], [8].

A plane section σ in $T_p\tilde{M}$ of a Sasakian manifold \tilde{M} is called a φ -section if it is spanned by X and φX , where X is a unit tangent vector field orthogonal to ξ . The sectional curvature $\tilde{K}(\sigma)$ w.r.t. a φ -section σ is called a φ -sectional curvature. If a Sasakian manifold \tilde{M} has constant φ -sectional curvature c , then it is called a *Sasakian space form* and is denoted by $\tilde{M}(c)$.

The curvature tensor \tilde{R} of a Sasakian space form $\tilde{M}(c)$ is given by [1]:

$$\begin{aligned} \tilde{R}(X, Y)Z &= \frac{c+3}{4}(g(Y, Z)X - g(X, Z)Y) + \\ &+ \frac{c-1}{4}(\eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X + g(X, Z)\eta(Y)\xi - g(Y, Z)\eta(X)\xi) \\ &+ g(\varphi Y, Z)\varphi X - g(\varphi X, Z)\varphi Y - 2g(\varphi X, Y)\varphi Z, \end{aligned}$$

for any tangent vector fields X, Y, Z to $\tilde{M}(c)$.

An n -dimensional submanifold M of a Sasakian space form $\tilde{M}(c)$ is called a *C-totally real submanifold* if ξ is a normal vector field on M . A direct consequence of this definition is that $\varphi(TM) \subset T^\perp M$, i.e. that M is an anti-invariant submanifold of $\tilde{M}(c)$, (hence their name of "contact"-totally real submanifolds); see e.g. [6].

As examples of Sasakian space forms we mention \mathbb{R}^{2m+1} and S^{2m+1} , with standard Sasakian structures.

Let a be a number > 1 . Put

$$\mu_a = \frac{\sqrt{a^2 - 1}}{\sqrt{2}} cn \left(ax, \frac{\sqrt{a^2 - 1}}{\sqrt{2}} \right).$$

Denote by P_a^n the *warped product* $I \times_{\mu_a} S^{n-1}(\frac{a^4-1}{4})$ with *warped function* μ_a for $n \geq 3$ and P_a^2 the warped product $I \times_{\mu_a} \mathbb{R}$.

The metric tensor g of P_a^n is then given by

$$g = dx^2 + \mu_a^2 g_0,$$

where x is the canonical coordinate of I and g_0 the canonical metric tensor of $S^{n-1}(\frac{a^4-1}{4})$ or of \mathbb{R} , respectively. Since $S^{n-1}(\frac{a^4-1}{4})$ is conformally flat, there exist local coordinate systems $\{u_2, \dots, u_n\}$ such that the metric tensor g_0 is given by

$$g_0 = E^2(du_2^2 + du_3^2 + \dots + du_n^2)$$

(when $n = 2$, we choose $E = 1$).

Therefore the metric tensor of P_a^n is given by

$$g = dx^2 + \mu_a^2 E^2(du_2^2 + du_3^2 + \dots + du_n^2).$$

Let

$$e_1 = \frac{\partial}{\partial x}, e_2 = \frac{1}{E\mu_a} \frac{\partial}{\partial u_2}, \dots, e_n = \frac{1}{E\mu_a} \frac{\partial}{\partial u_n}.$$

Then $\{e_1, \dots, e_n\}$ forms an orthonormal frame field on P_a^n .

We define a symmetric bilinear function $\sigma : TP_a^n \times TP_a^n \rightarrow TP_a^n$, by putting

$$\sigma(e_1, e_1) = 3\mu_a e_1, \quad \sigma(e_1, e_i) = \sigma(e_i, e_1) = \mu_a e_i, \quad \sigma(e_i, e_j) = \delta_{ij} \mu_a e_1, \quad i, j = \overline{2, n}. \quad (2)$$

Then $g(\sigma(X, Y), Z)$ is both linear and totally symmetric in X, Y, Z .

Then there exists a C-totally real isometric immersion $p_a : P_a^n \rightarrow S^{2n+1}$ whose second fundamental form is given by $h = \varphi\sigma$, where σ is defined by (2).

Applying Gauss' equation and (2), we obtain the equality case for C-totally real isometric immersions.

An orthonormal frame field $e_1, \dots, e_n, e_{1*}, \dots, e_{n*}, e_{2n+1}$ is called an *adapted frame field* if e_1, \dots, e_n are orthonormal tangent vector fields and $e_{1*}, \dots, e_{n*}, e_{2n+1}$ are normal vector fields given by

$$e_{1*} = \varphi e_1, \dots, e_{n*} = \varphi e_n, e_{2n+1} = \xi$$

§3. Main results

Theorem 1. *If M^n is a C-totally real submanifold of a Sasakian space form $\tilde{M}^{2n+1}(c)$, then the mean curvature H and the scalar curvature τ of M satisfy*

$$(3) \quad \|H\|^2 \geq \frac{2(n+2)}{n^2(n-1)}\tau - \left(\frac{n+2}{n}\right)\left(\frac{c+3}{4}\right).$$

Moreover the equality sign holds if and only if, with respect an adapted frame field $e_1, \dots, e_n, e_{1*}, \dots, e_{n*}, e_{2n+1} = \xi$ with e_{1*} parallel to H , the second fundamental form of M^n in $\tilde{M}^{2n+1}(c)$ takes the following form :

$$\begin{aligned} h(e_1, e_1) &= 3\lambda e_{1*}, & h(e_2, e_2) &= \dots = h(e_n, e_n) = \lambda e_{1*}, \\ h(e_1, e_j) &= \lambda e_{j*}, & h(e_j, e_k) &= 0, \quad 2 \leq j \neq k \leq n, \end{aligned}$$

with $\lambda \in C^\infty(M)$.

Proof. Let M^n be a C-totally real submanifold of a Sasakian space forms $\tilde{M}^{2n+1}(c)$, and $e_1, \dots, e_n, e_{1*}, \dots, e_{n*}, e_{2n+1} = \xi$ a local adapted frame field on M^n .

Put $h_{jk}^i = g(h(e_j, e_k), e_{i*})$.

Then, by

$$(4) \quad A_{\varphi X}Y = -\varphi h(X, Y) = A_{\varphi Y}X \quad \forall X, Y \in \Gamma(TM),$$

we have

$$h_{jk}^i = h_{ik}^j = h_{ij}^k, \quad i, j, k = \overline{1, n}.$$

From the definition of the mean curvature function we have

$$n^2 \|H\|^2 = \sum_i \left(\sum_j (h_{jj}^i)^2 + 2 \sum_{j < k} h_{jj}^i h_{kk}^i \right).$$

From the equation of Gauss we have

$$2\tau = n(n-1) \left(\frac{c+3}{4} \right) + n^2 \|H\|^2 - \|h\|^2 = n(n-1) \left(\frac{c+3}{4} \right) + n^2 \|H\|^2 - \sum_{i,j,k=1}^n (h_{jk}^i)^2.$$

Thus, by applying precedent relations, we obtain

$$\tau = \frac{n(n-1)}{2} \left(\frac{c+3}{4} \right) + \sum_i \sum_{j < k} h_{jj}^i h_{kk}^i - \sum_{i \neq j} (h_{jj}^i)^2 - 3 \sum_{i < j < k} (h_{jk}^i)^2.$$

Let $m = \frac{n+2}{n-1}$. Then, we get

$$\begin{aligned} n^2 \|H\|^2 - m \left(2\tau - n(n-1) \left(\frac{c+3}{4} \right) \right) &= \sum_i (h_{ii}^i)^2 + (1+2m) \sum_{i \neq j} (h_{jj}^i)^2 \\ &\quad + 6m \sum_{i < j < k} (h_{jk}^i)^2 - 2(m-1) \sum_i \sum_{j < k} h_{jj}^i h_{kk}^i \end{aligned}$$

$$\begin{aligned}
 &= \sum_i (h_{ii}^i)^2 + 6m \sum_{i < j < k} (h_{jk}^i)^2 + (m-1) \sum_i \sum_{j < k} (h_{jj}^i - h_{kk}^i)^2 \\
 &+ (1 + 2m - (n-2)(m-1)) \sum_{j \neq i} (h_{jj}^i)^2 - 2(m-1) \sum_{j \neq i} h_{jj}^i h_{jj}^i \\
 &= 6m \sum_{i < j < k} (h_{jk}^i)^2 + (m-1) \sum_{i \neq j, k} \sum_{j < k} (h_{jj}^i - h_{kk}^i)^2 \\
 &+ \frac{1}{n-1} \sum_{j \neq i} (h_{ii}^i - (n-1)(m-1)h_{jj}^i)^2 \geq 0
 \end{aligned}$$

which implies inequality (3). We see that the equality sign of (3) holds if and only if $h_{ii}^i = 3h_{jj}^i, h_{jk}^i = 0$, for distinct i, j, k . In particular, if choose e_1, \dots, e_n in such way that φe_1 is parallel to the mean curvature vector H , we also have $h_{kk}^j = 0$ for $j > 1, k = \overline{1, n}$. \square

Theorem 2. *Let $i : M^n \rightarrow S^{2n+1}$ be a C-totally real isometric immersion satisfying the equality case*

$$\|H\|^2 = \frac{2(n+2)}{n^2(n-1)}\tau - \left(\frac{n+2}{n}\right).$$

Then either M is a totally geodesic submanifold and hence M is a locally isometric to the real projective space $\mathbb{R}P^n(1)$ or the set U of non-totally geodesic points in M is a dense subset of M , U is an open portion of a P_a^n with $a > 1$ and, up to rigid motions of S^{2n+1} , the immersion i is given by p_a .

Proof. It follows from Theorem 1 that the function $\phi = \left(\binom{n}{n-2}\right)^2 \|H\|^2 = \lambda^2$ is a well-defined function on M . If the function ϕ vanishes identically, then M is a totally geodesic submanifold of S^{2n+1} . So, for simplicity, we may assume from now on that M is non-totally geodesic, i.e. $\phi \neq 0$. Thus, $U = \{p \in M \mid \phi(p) \neq 0\}$ is a non-empty open subset of M .

Let $\omega^1, \dots, \omega^n$ denote the dual 1-forms of e_1, \dots, e_n and denoted by (ω_B^A) , $A, B = 1, \dots, n, 1^*, \dots, n^*, 2n+1$, the connection forms on M defined by

$$\tilde{\nabla} e_i = \sum_{j=1}^n \omega_i^j e_j + \sum_{j=1}^n \omega_i^{j*} e_{j^*}, \quad \tilde{\nabla} e_{i^*} = \sum_{j=1}^n \omega_{i^*}^j e_j + \sum_{j=1}^n \omega_{i^*}^{j*} e_{j^*}, \quad i = 1, \dots, n,$$

where $\omega_i^j = -\omega_j^i, \omega_{i^*}^{j*} = -\omega_{j^*}^{i^*}$

For a C-totally real submanifold M^n of a $S^{2n+1}(c)$, (4) yields

$$\omega_j^{i^*} = \omega_i^{j*}, \omega_i^j = \omega_{i^*}^{j*}, \omega_j^{i^*} = \sum_{k=1}^n h_{jk}^i \omega^k.$$

We find

$$(5) \quad \omega_1^{1^*} = 3\lambda\omega^1, \omega_i^{1^*} = \lambda\omega^i, \omega_i^{i^*} = \lambda\omega^1, \omega_j^{i^*} = 0, 2 \leq i \neq j \leq n.$$

By applying the equation of Codazzi, we obtain

$$(6) \quad e_1 \lambda = \lambda \omega_1^2(e_2) = \dots = \lambda \omega_1^n(e_n), \quad e_2 \lambda = \dots = e_n \lambda = 0,$$

$$(7) \quad \omega_1^j(e_k) = 0, \quad 1 < j \neq k \leq n.$$

By precedent formulas, one gets

$$(8) \quad \omega_1^j = e_1(\ln \lambda) \omega^j, \quad j = \overline{2, n}.$$

Let \mathcal{D} denote the distribution spanned by φH and \mathcal{D}^\perp denote the orthogonal complementary distribution of \mathcal{D} on U . Then \mathcal{D} and \mathcal{D}^\perp are spanned by $\{\varphi H\}$ and $\{e_2, \dots, e_n\}$, respectively.

Lemma 3. *On U we have*

(1) *the integral curves of φH (or, equivalently, of e_1) are geodesics of M ,*

(2) *the distributions \mathcal{D} and \mathcal{D}^\perp are both integrable,*

(3) *there exist local coordinate systems $\{x_1, \dots, x_n\}$ such that :*

(a) *\mathcal{D} is spanned by $\{\frac{\partial}{\partial x}\}$ and \mathcal{D}^\perp is spanned by $\{\frac{\partial}{\partial x_2}, \dots, \frac{\partial}{\partial x_n}\}$,*

(b) *$e_1 = \frac{\partial}{\partial x}$, $\omega^1 = dx$,*

(c) *the metric tensor g takes the form : $g = dx^2 + \sum_{j,k=2}^n g_{jk} dx_j dx_k$, where $x = x_1$,*

(4) *λ is a function of x and it satisfies*

$$\frac{d^2 \lambda}{dx^2} + 2\lambda^3 + \lambda = 0$$

Proof. (8) and Cartan's structure equations imply $d\omega^1 = 0$ and $\nabla_{e_1} e_1 = 0$.

Therefore, the integral curves of e_1 are geodesics. This proves statement (1).

For any $j, k > 1$, (7) implies $\langle [e_j, e_k], e_1 \rangle = \omega_j^1(e_k) - \omega_k^1(e_j) = 0$, which shows that the distribution \mathcal{D}^\perp is integrable. The integrability of \mathcal{D} is obvious, since \mathcal{D} is a 1-dimensional distribution. This proves (2).

Since \mathcal{D} is 1-dimensional, there exists a local coordinate system $\{y_1, \dots, y_n\}$ such that $e_1 = \frac{\partial}{\partial y_1}$. Because \mathcal{D}^\perp is integrable, there also exists a local coordinate system

$\{z_1, \dots, z_n\}$ such that $\{\frac{\partial}{\partial z_2}, \dots, \frac{\partial}{\partial z_n}\}$ span \mathcal{D}^\perp . Put

$$x_1 = y_1, x_2 = z_2, \dots, x_n = z_n.$$

Then $\{x_1, \dots, x_n\}$ is a local coordinate system satisfying the conditions given in (3).

From (6) and statement (3), we see that the function λ depends only on $x (= x_1)$; thus $\lambda = \lambda(x)$. Let λ' and λ'' denote the first and second derivatives of λ with respect to x . By taking the exterior differentiation of (8) and using (5), (8) and Cartan's structure equations, we find

$$(\ln \lambda)'' + (\ln \lambda)'^2 = -1 - 2\lambda^2$$

which is equivalent to (4).

Come back to the proof of Theorem 2.

By reference to [4], the solution of the equation (4) is

$$\lambda = \frac{\sqrt{a^2 - 1}}{\sqrt{2}} cn \left(ax + b, \frac{\sqrt{a^2 - 1}}{\sqrt{2}} \right),$$

where a, b are constants with $a > 1$.

The rigidity theorem for C -totally real immersions in S^{2n+1} achieves the proof. \square

In a forthcoming paper, we investigate submanifolds in \mathbb{R}^{2n+1} satisfying the equality case of Theorem 1.

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