

Linear connections on the cotangent bundle of order two $(T^{*2}M, \pi^{*2}, M)$

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Abstract. In the recent theory on the Hamilton space of the order two (see R.Miron [9], [10], where $k = 2$, and R. Miron and his partners [11]), a linear connection has the smallest possible number of sets of components, namely three, given by $(H^a_{bc}, C^a_{bc}, C_a{}^{bc})$, $(a, b, c = 1, \dots, n; n = \dim M)$. In this paper a linear connection in the differential geometry of the 2-cotangent bundle $(T^{*2}M, \pi^{*2}, M)$, needed in the study of the Hamilton spaces of the order two, will have nine sets of coefficients. The whole calculus: the parallelism of vector fields, the torsion, the curvature, the structure equations, the Ricci and Bianchi identities, etc., can be based of the set of these nine coefficients (see [6]).

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1 The manifold $T^{*2}M$. Nonlinear connection.

Let M be a real differentiable manifold of dimension n . A point of M will be denoted by x and its local coordinate system by (U, φ) , $\varphi(x) = (x^a)$. The indices a, b, \dots run over set $\{1, \dots, n\}$ and Einstein convention of summarizing is adapted all over this work. Let (TM, π, M) be the tangent bundle of the manifold M and (T^*M, π^*, M) its cotangent bundle, [11], [15].

Definition 1.1 ([11]) We call the dual bundle of the 2-tangent bundle (T^2M, π^2, M) , the differentiable bundle $(T^{*2}M, \pi^{*2}, M)$ whose total space is

$$(1.1) \quad T^{*2}M = TM \times_M T^*M.$$

Sometimes we denote $(T^{*2}M, \pi^{*2}, M)$ by $T^{*2}M$. A point $u \in T^{*2}M$ will be denoted by $u = (x, y, p)$ having the local coordinates (x^a, y^a, p_a) . The projection $\pi^{*2}(u) = \pi^{*2}(x, y, p) = x$. Evidently, we take the projections on the factors of the fibered products (1.1): $\pi_1^{*2} : T^{*2}M \rightarrow TM$, $\pi : TM \rightarrow M$ as being $\pi_1^{*2}(x, y, p) = (x, y)$ and $\pi^*(x, y) = x$; also, $\bar{\pi}^* : T^{*2}M \rightarrow T^*M$ is given by $\bar{\pi}^*(u) = \bar{\pi}^*(x, y, p) = (x, p)$.

The change of local coordinates on the manifold $T^{*2}M$ is:

$$(1.2) \quad \begin{cases} \tilde{x}^a = \tilde{x}^a(x^1, \dots, x^n), \det\left(\frac{\partial \tilde{x}^a}{\partial x^b}\right) \neq 0, \\ \tilde{y}^a = \frac{\partial \tilde{x}^a}{\partial x^b} y^b, \\ \tilde{p}_a = \frac{\partial x^b}{\partial \tilde{x}^a} p_b. \end{cases}$$

The dimension of the manifold $T^{*2}M$ is $3n$.

The null section $0 : M \rightarrow T^{*2}M$ of the projection π^{*2} is defined by $0 : (x) \in M \rightarrow (x, 0, 0) \in T^{*2}M$ we denote by $\widetilde{T^{*2}M} = T^{*2}M \setminus \{0\}$.

Let us consider the tangent bundle of the differentiable manifold $T^{*2}M$, $(TT^{*2}M, \tau^{*2}, T^{*2}M)$, where τ^{*2} is the canonical projection and the vertical distribution $V : u \in T^{*2}M \rightarrow V(u) \subset T_u T^{*2}M$, generated by the vector fields $\left\{ \frac{\partial}{\partial y^a} \Big|_u, \frac{\partial}{\partial p_a} \Big|_u \right\}$, $\forall u \in T^{*2}M$. As usually, the natural basis, let us denote

$$(1.3) \quad \partial_a = \frac{\partial}{\partial x^a}, \dot{\partial}_a = \frac{\partial}{\partial y^a}, \dot{\partial}^a = \frac{\partial}{\partial p_a}.$$

By means of (1.2), we can consider the following subdistributions of V :

$$(1.4) \quad V_1 : u \in T^{*2}M \rightarrow V_1(u) \subset T_u T^{*2}M,$$

and

$$(1.4') \quad W_2 : u \in T^{*2}M \rightarrow W_2(u) \subset T_u T^{*2}M,$$

locally generated by the vector fields $\left\{ \dot{\partial}_a \Big|_u, u \in T^{*2}M \right\}$ and $\left\{ \dot{\partial}^a \Big|_u, u \in T^{*2}M \right\}$, respectively. Clearly, we have

$$(1.5) \quad V(u) = V_1(u) \oplus W_2(u), \forall u \in T^{*2}M.$$

Let us consider the following forms

$$(1.6) \quad \omega = p_a dx^a \text{ (Liouville 1-form),}$$

$$(1.7) \quad \theta = d\omega = dp_a \wedge dx^a.$$

Theorem 1.1 ([11]) 1°. *The differential forms ω and θ are globally defined on the manifold $T^{*2}M$.*

2°. *The 2-form θ is closed and rank θ is $2n$.*

3°. *θ is a presymplectic structures on $T^{*2}M$.*

Also, the following $\mathcal{F}(T^{*2}M)$ -linear mapping

$$J : \mathcal{X}(T^{*2}M) \rightarrow \mathcal{X}(T^{*2}M),$$

defined by

$$(1.8) \quad J(\partial_a) = \dot{\partial}_a, \quad J\left(\dot{\partial}_a\right) = 0, \quad J\left(\dot{\partial}^a\right) = 0, \quad \forall u \in \widetilde{T^{*2}M},$$

has geometrical meaning. It is not difficult to prove:

Theorem 1.2 1°. J is a tensor field of type $(1, 1)$ on manifold $T^{*2}M$.

2°. J is a tangent structure on $T^{*2}M$, i.e. $J_0J = 0$.

3°. J is a integrable structure.

4°. $J_0J = J^2 = 0$.

5°. $\text{Ker}J = V_1 \oplus W_2$, $\text{Im}J = V_1$.

With these object fields we can construct the geometry of the manifold $T^{*2}M$.

Now, we extend the classical definition [14], of the nonlinear connection on the total space of the dual bundle $(T^{*2}M, \pi^{*2}, M)$.

Definition 1.2 A nonlinear connection of the manifold $T^{*2}M$ is a regular distribution N on $T^{*2}M$, supplementary to the vertical distribution V , i.e.

$$(1.9) \quad T_u T^{*2}M = N(u) \oplus V(u), \quad \forall u \in T^{*2}M.$$

Taking into account (1.5) it follows that the distribution N has the property

$$(1.10) \quad T_u T^{*2}M = N(u) \oplus V_1(u) \oplus W_2(u), \quad \forall u \in T^{*2}M.$$

Therefore, the main geometrical objects on $T^{*2}M$ will be reported to the direct sum (1.10) of vector spaces.

We denote by

$$(1.11) \quad \left\{ \frac{\delta}{\delta x^a}, \frac{\partial}{\partial y^a}, \frac{\partial}{\partial p_a} \right\}, \quad (a = 1, \dots, n),$$

a local adapted basis to N, V_1, W_2 . Clearly, we have

$$(1.12) \quad \frac{\delta}{\delta x^a} = \frac{\partial}{\partial x^a} - N_a^b \frac{\partial}{\partial y^b} + N_{ab} \frac{\partial}{\partial p_b}.$$

The sistem of functions $(N_a^b(x, y, p), N_{ab}(x, y, p))$ are the coefficients of the nonlinear connection N .

With respect to the coordinate transformations (1.2), we have the rule:

$$(1.12') \quad \frac{\delta}{\delta x^a} = \frac{\partial \tilde{x}^b}{\partial x^a} \frac{\delta}{\delta \tilde{x}^b}, \quad \frac{\partial}{\partial y^a} = \frac{\partial \tilde{x}^b}{\partial x^a} \frac{\partial}{\partial \tilde{y}^b}, \quad \frac{\partial}{\partial p_a} = \frac{\partial x^a}{\partial \tilde{x}^b} \frac{\partial}{\partial \tilde{p}_b}.$$

Theorem 1.3 With respect to (1.2) the coefficients (N_a^b, N_{ab}) of a nonlinear connection N on $T^{*2}M$ obey the rule

$$(1.13) \quad \begin{aligned} \tilde{N}_c^a \frac{\partial \tilde{x}^c}{\partial x^b} &= N_b^c \frac{\partial \tilde{x}^a}{\partial x^c} - \frac{\partial \tilde{y}^a}{\partial x^b}, \\ \tilde{N}_{ab} &= \frac{\partial x^c}{\partial \tilde{x}^a} \frac{\partial x^d}{\partial \tilde{x}^b} N_{cd} + p_c \frac{\partial^2 x^c}{\partial \tilde{x}^a \partial \tilde{x}^b}. \end{aligned}$$

Conversely, if the system of functions (N_b^a, N_{ab}) are given on the every domain of local chart of the manifold $T^{*2}M$, such that the equations (1.13) hold, then (N_b^a, N_{ab}) are the coefficients of a nonlinear connection on $T^{*2}M$.

Assuming that the manifold M is paracompact it follows that the manifold $T^{*2}M$ is paracompact, too. Let $\gamma_{ab}(x)$, $x \in M$ be a Riemannian metric on M and $\gamma_{bc}^a(x)$ its Christoffel symbols. Setting

$$(1.14) \quad f_b = \gamma_{bc}^a(x) p_a y^c,$$

then, the system of functions

$$(1.15) \quad N_b^a = \dot{\partial}^a f_b, \quad N_{ab} = \dot{\partial}_b f_a,$$

are geometrical object fields on $T^{*2}M$, having the rules of transformations (1.13), with respect to the changing of local coordinates (1.2). Hence:

Theorem 1.4 *If the base manifold M is paracompact, then there exist nonlinear connection on the manifold $T^{*2}M$.*

From now we denote the basis (1.11) by:

$$(1.11') \quad \left\{ \delta_a, \dot{\partial}_a, \dot{\partial}^a \right\}.$$

The dual basis of the adapted basis (1.11) is given by

$$(1.16) \quad \{ dx^a, \delta y^a, \delta p_a \},$$

where

$$(1.16') \quad \delta y^a = dy^a + N_b^a dx^b, \quad \delta p_a = dp_a - N_{ba} dx^b.$$

With respect to (1.2), the covector fields (1.16) are transformed by the rules:

$$(1.16'') \quad d\tilde{x}^a = \frac{\partial \tilde{x}^a}{\partial x^b} dx^b, \quad \delta \tilde{y}^a = \frac{\partial \tilde{x}^a}{\partial x^b} \delta y^b, \quad \delta \tilde{p}_a = \frac{\partial x^b}{\partial \tilde{x}^a} \delta p_b,$$

2 The Algebra of distinguished tensor fields.

Let N be a nonlinear connection on $T^{*2}M$. It determines, at every point $u \in T^{*2}M$, the direct sum (1.10) of the linear space $T_u(T^{*2}M)$.

A vector field $X \in \chi(T^{*2}M)$ and an one form $\omega \in \chi^*(T^{*2}M)$ uniquely can be written in the form:

$$(2.1) \quad \begin{aligned} X &= X^H + X^{V_1} + X^{W_2}, \\ \omega &= \omega^H + \omega^{V_1} + \omega^{W_2}. \end{aligned}$$

Clearly if h, v_1, w_2 are the projectors determined by the direct decomposition (1.10), we have

$$(2.2) \quad \begin{aligned} X^H &= hX, \quad X^{V_1} = v_1X, \quad X^{W_2} = w_2X, \\ \omega^H &= \omega \circ h, \quad \omega^{V_1} = \omega \circ v_1, \quad \omega^{W_2} = \omega \circ w_2. \end{aligned}$$

Definition 2.1 ([10]) A distinguished tensor field (briefly, d -tensor field) on the manifold $T^{*2}M$ is a d -tensor field T of type (r, s) on $T^{*2}M$, with the property:

$$(2.3) \quad \begin{aligned} T \left(\overset{1}{\omega}, \dots, \overset{r}{X}, \overset{1}{X}, \dots, \overset{s}{X} \right) &= T \left(\overset{1}{\omega}^H, \dots, \overset{r}{\omega}^{W_2}, \overset{1}{X}^H, \dots, \overset{s}{X}^{W_2} \right), \\ \forall \overset{1}{\omega}, \dots, \overset{r}{\omega} \in \chi^*(T^{*2}M), \quad \forall \overset{1}{X}, \dots, \overset{s}{X} \in \chi(T^{*2}M). \end{aligned}$$

For instance, every components X^H, X^{V_1}, X^{W_2} of a vector field X is a d -tensor field of type $(1, 0)$, and every components $\omega^H, \omega^{V_1}, \omega^{W_2}$ of a 1-form ω is a d -tensor field of type $(0, 1)$.

In the adapted basis $\left(\delta_a, \dot{\partial}_a, \dot{\partial}^a \right)$ and its dual basis $(dx^a, \delta y^a, \delta p_a)$ a d -tensor field T of type (r, s) can written in the form:

$$(2.4) T = T_{b_1 \dots b_s}^{a_1 \dots a_r}(x, y, p) \delta_{a_1} \otimes \dots \otimes \dot{\partial}^{b_s} \otimes dx^{b_1} \otimes \dots \otimes \delta p_{a_r},$$

where

$$T_{b_1 \dots b_s}^{a_1 \dots a_r}(x, y, p) = T \left(dx^{b_1}, \dots, \delta p_{a_r}, \delta_{a_1}, \dots, \dot{\partial}^{b_s} \right).$$

It follows that the set $\left\{ 1, \delta_a, \dot{\partial}_a, \dot{\partial}^a \right\}$ generates **the algebra** of the d -tensor fields over the ring of functions $\mathcal{F}(T^{*2}M)$, (see R. Miron [9], [10]).

With respect to the transformation of the coordinates on $T^{*2}M$, the local coefficients $T_{b_1 \dots b_s}^{a_1 \dots a_r}$ of T are transformed by classical rule:

$$(2.5) \quad \tilde{T}_{d_1 \dots d_s}^{c_1 \dots c_r} = \frac{\partial \tilde{x}^{c_1}}{\partial x^{a_1}} \dots \frac{\partial \tilde{x}^{c_r}}{\partial x^{a_r}} \frac{\partial x^{b_1}}{\partial \tilde{x}^{d_1}} \dots \frac{\partial x^{b_s}}{\partial \tilde{x}^{d_s}} T_{b_1 \dots b_s}^{a_1 \dots a_r}.$$

Examples

1. If $f \in \mathcal{F}(T^{*2}M)$, then every set of functions $\delta_a f, \dot{\partial}_a, \dot{\partial}^a f$ is a d -covector field, and $\dot{\partial}^a f$ is a d -vector field.

2. Let us consider a Riemann structure \mathbb{G} on $T^{*2}M$ and assume that the distributions N, V_1, W_2 are orthogonal in pairs, with respect to \mathbb{G} :

$$(2.6) \quad \begin{aligned} \mathbb{G}(X^H, Y^{V_1}) &= \mathbb{G}(X^H, Y^{W_2}) = \mathbb{G}(X^{V_1}, Y^{W_2}) = 0, \\ \forall X, Y &\in \chi(T^{*2}M). \end{aligned}$$

In this case \mathbb{G} can be uniquely written as a sum of d -tensors:

$$(2.7) \quad \mathbb{G} = \mathbb{G}^H + \mathbb{G}^{V_1} + \mathbb{G}^{W_2},$$

where, for any $X, Y \in T^{*2}M$, we have

$$(2.7') \quad \mathbb{G}^H(X, Y) = \mathbb{G}(X^H, Y^H), \mathbb{G}^{V_1}(X, Y) = \mathbb{G}(X^{V_1}, Y^{V_1}), \mathbb{G}^{W_2}(X, Y) = \mathbb{G}(X^{W_2}, Y^{W_2}).$$

Consequently, in the adapted cobasis, \mathbb{G} can be uniquely written as

$$(2.8) \quad \mathbb{G} = \underset{(0)}{g_{ab}} dx^a \otimes dx^b + \underset{(1)}{g_{ab}} \delta y^a \otimes \delta y^b + \underset{(2)}{g^{ab}} \delta p_a \otimes \delta p_b,$$

where

$$(2.8') \quad \underset{(\alpha)}{g_{ab}}(x, y, p) = \underset{(\alpha)}{g_{ba}}(x, y, p), \|\underset{(\alpha)}{g_{ab}}\| = \|\underset{(\alpha)}{g^{ab}}\|^{-1},$$

$$(2.8'') \quad \text{rank } \|\underset{(\alpha)}{g_{ab}}\| = n, (\alpha = 0, 1, 2).$$

The quantities $\underset{(\alpha)}{g_{ab}}, (\alpha = 0, 1, 2)$, are d -tensors of type $(0, 2)$ on $T^{*2}M$, and $\underset{(\alpha)}{g^{ab}}, (\alpha = 0, 1, 2)$, are d -tensors of type $(2, 0)$ on $T^{*2}M$.

3 The almost contact structure \mathbb{F}

The nonlinear connection N being fixed we have the decomposition (1.9), (1.10) and the corresponding adapted basis (1.11).

Let us consider the $\mathcal{F}(T^{*2}M)$ -linear mapping:

$$\mathbb{F} : \chi(T^{*2}M) \longrightarrow \chi(T^{*2}M),$$

determined by

$$(3.1) \quad \mathbb{F}(\delta_a) = -\dot{\partial}_a, \mathbb{F}\left(\dot{\partial}_a\right) = \delta_a, \mathbb{F}\left(\dot{\partial}^a\right) = 0.$$

Then, we deduce

Theorem 3.1 *The mapping \mathbb{F} has the following properties:*

1°. *It is globally defined on $T^{*2}M$.*

- 2°. \mathbb{F} is a tensor field of type $(1, 1)$.
- 3°. $\text{Ker } \mathbb{F} = W_2$, $\text{Im } \mathbb{F} = N \oplus V_1$.
- 4°. $\text{rank } \mathbb{F} = 2n$.
- 5°. $\mathbb{F}^3 + \mathbb{F} = 0$.

Proof. See [11] pg.259.

We can say that \mathbb{F} is a **natural almost contact structure** determined by the nonlinear connection N .

Remark 3.1 In the case when we have a Riemann structure \mathbb{G} on $T^{*2}M$ and the following relation holds

$$(3.2) \quad \mathbb{G}(\mathbb{F}X, Y) = -\mathbb{G}(X, \mathbb{F}Y), \forall X, Y \in \chi(\widetilde{T^{*2}M}),$$

then the pair (\mathbb{G}, \mathbb{F}) is a **Riemann almost contact structure** on $\widetilde{T^{*2}M}$. The manifold $T^{*2}M$ endowed with these structure gives us the geometrical **model** $\{T^{*2}M, \mathbb{G}, \mathbb{F}\}$ for this space.

By direct calculus, we get:

Theorem 3.2 *If \mathbb{G} is a Riemann structure on $T^{*2}M$ given in the adapted cobasis (1.15) by*

$$\mathbb{G} = \underset{(00)}{g_{ab}} dx^a \otimes dx^b + \underset{(01)}{g_{ab}} dx^a \otimes \delta y^a + \underset{(02)}{g_a^b} dx^a \otimes \delta p_b + \dots + \underset{(22)}{g^{ab}} \delta p_a \otimes \delta p_b,$$

then, the pair (\mathbb{G}, \mathbb{F}) is a Riemann almost structure on $\widetilde{T^{*2}M}$ if and only if in the adapted basis determined by N and V the tensor \mathbb{G} has the form

$$(3.3) \quad \mathbb{G} = g_{ab} dx^a \otimes dx^b + g_{ab} \delta y^a \otimes \delta y^b + h^{ab} \delta p_a \otimes \delta p_b.$$

where $g_{ab}(x, y, p)$, $h^{ab}(x, y, p)$ have the propeties (2.8') and (2.8'').

Corollary 3.1 *With respect to the Riemann structure (3.3) the distributions N, V_1, W_2 are orthogonal in pairs.*

4 N -linear connections on $T^{*2}M$

A linear connection on $T^{*2}M$ is an application

$$D : \chi(T^{*2}M) \times \chi(T^{*2}M) \longrightarrow \chi(T^{*2}M), (X, Y) \longmapsto D_X Y,$$

with the properties:

1. $D_{X_1+X_2} Y = D_{X_1} Y + D_{X_2} Y$,
 $D_{fX} Y = f D_X Y, \forall f \in \mathcal{F}(T^{*2}M), \forall X, X_1, X_2, Y \in \chi(T^{*2}M)$.
2. $D_X (Y_1 + Y_2) = D_X Y_1 + D_X Y_2, \forall X, Y_1, Y_2 \in \chi(T^{*2}M)$.
3. $D_X (fY) = (Xf)Y + f D_X Y, \forall X, Y \in \chi(T^{*2}M), \forall f \in \mathcal{F}(T^{*2}M)$.

We consider $X, Y \in \chi(T^{*2}M)$. With respect to decomposition of type (2.1), we have

$$(4.1) \quad D_X Y = \sum_{\alpha=0}^2 (D_{X^H} Y^{V_\alpha} + D_{X^{V_1}} Y^{V_\alpha} + D_{X^{W_2}} Y^{V_\alpha}),$$

where $V_0 = H$ and $V_2 = W_2$.

The components $D_{X^H} Y^{V_\alpha}$, $D_{X^{V_1}} Y^{V_\alpha}$, $D_{X^{W_2}} Y^{V_\alpha}$, ($V_0 = H$, $V_2 = W_2$), are vector fields not necessary distinguished.

The linear connection D on $T^{*2}M$ is uniquely determined by its 27 coefficients, written in the adapted basis .

To work with these 27 coefficients is not imposible, but is laborious.

We will use in continuation the N -linear connections whose coefficients are much easy to shunt.

Let N be a nonlinear connection on $T^{*2}M$.

Definition 4.1 A linear connection D on $T^{*2}M$ is called an N -linear connection if it preserves by parallelism the horizontal and vertical distributions N, V_1 and W_2 on $T^{*2}M$.

By the general theory of connections on manifolds, the horizontal and vertical distributions are preserves by parallelism if for any $X \in \chi(T^{*2}M)$, D_X carries the horizontal vector fields to the horizontal vector fields and the vertical vector fields to the vertical vector fields. Thus $D_X Y^H$ is always an horizontal vector field, and $D_X Y^{V_\beta}$ are verticals, ($\beta = 1, 2$; $V_2 = W_2$).

Obviously, the local description of an N -linear connection $D\Gamma(N)$ on $T^{*2}M$ is given by **nine** unique adapted **coefficients**:

$$(4.2) \quad D\Gamma(N) := \begin{matrix} H^a{}_{bc}, H^a{}_{bc}, H^a{}_{bc}, C^a{}_{bc}, C^a{}_{bc}, C^a{}_{bc}, C^a{}_{bc}, C^a{}_{bc}, C^a{}_{bc} \\ (00) \quad (10) \quad (20) \quad (01) \quad (11) \quad (21) \quad (02) \quad (12) \quad (22) \end{matrix}.$$

We have

Theorem 4.1 1°. An N -linear connection D on $T^{*2}M$ can be uniquely represented in the adapted basis $(\delta_a, \dot{\partial}_a, \dot{\partial}^a)$ in the form

$$(4.3) \quad \begin{cases} D_{\delta_c} \delta_b = H^a{}_{bc} \delta_a, D_{\dot{\partial}_c} \dot{\partial}_b = H^a{}_{bc} \dot{\partial}_a, D_{\dot{\partial}^c} \dot{\partial}^b = -H^a{}_{bc} \dot{\partial}^a, \\ D_{\dot{\partial}_c} \delta_b = C^a{}_{bc} \delta_a, D_{\dot{\partial}_c} \dot{\partial}_b = C^a{}_{bc} \dot{\partial}_a, D_{\dot{\partial}_c} \dot{\partial}^b = -C^a{}_{bc} \dot{\partial}^a, \\ D_{\dot{\partial}^c} \delta_b = C^a{}_{bc} \delta_a, D_{\dot{\partial}^c} \dot{\partial}_b = C^a{}_{bc} \dot{\partial}_a, D_{\dot{\partial}^c} \dot{\partial}^b = -C^a{}_{bc} \dot{\partial}^a. \end{cases}$$

2°. With respect to the coordinate transformation (1.2), the coefficients $H^a{}_{bc}$, ($\alpha = 0, 1, 2$; $H^a{}_{bc} := H^a{}_{bc}$) obey the rule of transformation:

$$(4.4) \quad \tilde{H}^a{}_{de} \frac{\partial \tilde{x}^d}{\partial x^b} \frac{\partial \tilde{x}^e}{\partial x^c} = \frac{\partial \tilde{x}^a}{\partial x^e} H^e{}_{bc} - \frac{\partial^2 \tilde{x}^a}{\partial x^b \partial x^c}.$$

3°. The system of functions

$$C^a{}_{bc}, C^a{}_{bc}, (\alpha = 0, 1, 2; C^a{}_{bc} := C^a{}_{bc}; C^a{}_{bc} := C^a{}_{bc})$$

are d -tensor fields of type $(1, 2)$ and $(2, 1)$, respectively.

We have the following theorem of existence of N -linear connection on $T^{*2}M$.

Theorem 4.2 *If the manifold M is paracompact and N is a nonlinear connection on $T^{*2}M$ with coefficients N_b^a, N_{ab} , then there exists an N -linear connection on $T^{*2}M$.*

Proof. Since M is paracompact, there exists a linear connection on M of local coefficients, say $\Gamma_{bc}^a(x)$. Let $N_b^a(x, y, p)$ and $N_{ab}(x, y, p)$ be the local coefficients of the nonlinear connection N . We set $H_{(00)}^a{}_{bc} = \Gamma_{bc}^a(x)$, $H_{(10)}^a{}_{bc} = \dot{\partial}_b N_c^a$, $H_{(20)}^a{}_{bc} = \dot{\partial}^a N_{bc}$. Thus, we obtain three set of function which transform, with respect to (1.2), by (4.4). It result that $D\Gamma(N)$ given by

$$(4.5) \quad D\Gamma(N) = \left(\Gamma_{bc}^a(x), \dot{\partial}_b N_c^a, \dot{\partial}^a N_{bc}, 0, 0, 0, 0, 0, 0 \right),$$

defines an N -linear connection on $T^{*2}M$.

5 The h_α -, $v_{1\alpha}$ - and $w_{2\alpha}$ -covariant derivatives in the local adapted basis, $(\alpha = 0, 1, 2)$

The N -linear connection $D\Gamma(N)$ induces the linear connections on the d -tensors set of the 2-cotangent bundle $(T^{*2}M, \pi^{*2}, M)$, in a natural way. Thus, starting with a d -vector field X and a d -tensor field T , locally expressed by

$$(5.1) \quad X = X^{(0)a} \delta_a + X^{(1)a} \dot{\partial}_a + X_{(2)}^a \dot{\partial}^a,$$

$$(5.2) \quad T = T_{b_1 \dots b_s}^{a_1 \dots a_r}(x, y, p) \delta_{a_1} \otimes \dots \otimes \dot{\partial}^{b_s} \otimes dx^{b_1} \otimes \dots \otimes \delta p_{a_r},$$

we can define the covariante derivative

$$(5.3) \quad D_X T = \left\{ X^{(0)d} T_{b_1 \dots b_s}^{a_1 \dots a_r} |_{\alpha d} + X^{(1)d} T_{b_1 \dots b_s}^{a_1 \dots a_r} |_{\alpha d} + X_{(2)}^d T_{b_1 \dots b_s}^{a_1 \dots a_r} |_{\alpha d} \right\} \delta_{a_1} \otimes \dots \otimes \delta p_{a_r},$$

where

$$(5.4_0) \quad T_{b_1 \dots b_s}^{a_1 \dots a_r} |_{\alpha d} = \delta_d T_{b_1 \dots b_s}^{a_1 \dots a_r} + H_{(\alpha 0)}^{a_1}{}_{cd} T_{b_1 \dots b_s}^{ca_2 \dots a_r} + \dots + H_{(\alpha 0)}^{a_r}{}_{cd} T_{b_1 \dots b_s}^{a_1 \dots c} - H_{(\alpha 0)}^c{}_{b_1 d} T_{cb_2 \dots b_s}^{a_1 \dots a_r} - \dots - H_{(\alpha 0)}^c{}_{b_s d} T_{b_1 \dots c}^{a_1 \dots a_r},$$

$$(5.4_1) \quad T_{b_1 \dots b_s}^{a_1 \dots a_r} |_{\alpha d} = \dot{\partial}_d T_{b_1 \dots b_s}^{a_1 \dots a_r} + C_{(\alpha 1)}^{a_1}{}_{cd} T_{b_1 \dots b_s}^{ca_2 \dots a_r} + \dots + C_{(\alpha 1)}^{a_r}{}_{cd} T_{b_1 \dots b_s}^{a_1 \dots c} - C_{(\alpha 1)}^c{}_{b_1 d} T_{cb_2 \dots b_s}^{a_1 \dots a_r} - \dots - C_{(\alpha 1)}^c{}_{b_s d} T_{b_1 \dots c}^{a_1 \dots a_r},$$

$$(5.4_2) \quad \begin{aligned} T_{b_1 \dots b_s}^{a_1 \dots a_r} |^{\alpha d} &= \dot{\partial}^d T_{b_1 \dots b_r}^{a_1 \dots a_r} + C_{(\alpha 2) c}^{a_1 d} T_{b_1 \dots b_s}^{c a_2 \dots a_r} + \dots + C_{(\alpha 2) c}^{a_r d} T_{b_1 \dots b_s}^{a_1 \dots c} - \\ &- C_{(\alpha 2) b_1}^{c d} T_{c b_2 \dots b_s}^{a_1 \dots a_r} - \dots - C_{(\alpha 2) b_s}^{c d} T_{b_1 \dots c}^{a_1 \dots a_r}. \end{aligned}$$

Definition 5.1 The local derivative operators " \cdot ", " $|_{\alpha d}$ ", " $|_{\alpha d}$ " and " $|^{\alpha d}$ " are called the \mathbf{h}_{α} -, $\mathbf{v}_{1\alpha}$ - and $\mathbf{w}_{2\alpha}$ -covariant derivatives of $D\Gamma(N)$, ($\alpha = 0, 1, 2$).

Remark 5.1 (i) In the particular case if T is a function $f(x, y, p)$ on $T^{*2}M$, the preceding covariant derivatives reduce to

$$(5.5) \quad \begin{aligned} f_{|\alpha d} &= \delta_d f = \partial_d f - N^c_d \dot{\partial}_c, \\ f |_{\alpha d} &= \dot{\partial}_d f, f |^{\alpha d} = \dot{\partial}^d f, \forall f \in \mathcal{F}(T^{*2}M). \end{aligned}$$

(ii) Considering the d -tensor $T = Y$ like a d -tensor on $T^{*2}M$, locally expressed by

$$(5.6) \quad Y = Y^{(0)a} \delta_a + Y^{(1)a} \dot{\partial}_a + Y_a \dot{\partial}^a,$$

the following expressions of local covariant derivatives of $D\Gamma(N)$ hold good:

$$(5.7) \quad \begin{aligned} Y^{(0)a} |_{\alpha c} &= \delta_c Y^{(0)a} + Y^{(0)b} H_{(\alpha 0) bc}^a, Y^{(1)a} |_{\alpha c} = \delta_c Y^{(1)a} + Y^{(1)b} H_{(\alpha 0) bc}^a, \\ Y_{b|\alpha c} &= \delta_c Y_b - Y_a H_{(\alpha 0) bc}^a, \\ Y^{(0)a} |_{\alpha c} &= \dot{\partial}_c Y^{(0)a} + Y^{(0)b} C_{(\alpha 1) bc}^a, Y^{(1)a} |_{\alpha c} = \dot{\partial}_c Y^{(1)a} + Y^{(1)b} C_{(\alpha 1) bc}^a, \\ Y_b |_{\alpha c} &= \dot{\partial}_c Y_b - Y_a C_{(\alpha 1) bc}^a, \\ Y^{(0)a} |^{\alpha b} &= \dot{\partial}^b Y^{(0)a} + Y^{(0)c} C_{(\alpha 2) c}^{ab}, Y^{(1)a} |^{\alpha b} = \dot{\partial}^b Y^{(1)a} + Y^{(1)c} C_{(\alpha 2) c}^{ab}, \\ Y_b |^{\alpha b} &= \dot{\partial}^b Y_c - Y_a C_{(\alpha 2) c}^{ab}. \end{aligned}$$

Proposition 5.1 The quantities $T_{b_1 \dots b_s |^{\alpha d} }^{a_1 \dots a_r}$, $T_{b_1 \dots b_s}^{a_1 \dots a_r} |_{\alpha d}$, $T_{b_1 \dots b_s}^{a_1 \dots a_r} |^{\alpha d}$, ($\alpha = 0, 1, 2$) are d -tensor fields on $T^{*2}M$. The firsts six are of type $(r, s + 1)$, the last three are of type $(r + 1, s)$.

6 Metric N -linear connections

Definition 6.1 A metric structure on the manifold $T^{*2}M$ is a symmetric covariant tensor field \mathbb{G} of type $(0, 2)$ which is non degenerate at each point $u \in T^{*2}M$ and of constant signature on $T^{*2}M$. If \mathbb{G} is positive definite we say that it defines a Riemann structure on $T^{*2}M$.

Let us consider a metric structure \mathbb{G} on $T^{*2}M$ for which the distributions N, V_1, W_2 are much general then (3.3), namely it have the decomposition:

$$(6.1) \quad \mathbb{G}(X, Y) = \mathbb{G}(X^H, Y^H) + \mathbb{G}(X^{V_1}, Y^{V_1}) + \mathbb{G}(X^{W_2}, Y^{W_2}), \forall X, Y \in T^{*2}M.$$

With the other words, \mathbb{G} decomposes in a sum of three d -tensor fields:

- (0) \mathbb{G}^H of type $(0, 2)$ defined by $\mathbb{G}^H(X, Y) = \mathbb{G}(X^H, Y^H)$,
- (1) \mathbb{G}^{V_1} of type $(0, 2)$ defined by $\mathbb{G}^{V_1}(X, Y) = \mathbb{G}(X^{V_1}, Y^{V_1})$,
- (2) \mathbb{G}^{W_2} of type $(0, 2)$ defined by $\mathbb{G}^{W_2}(X, Y) = \mathbb{G}(X^{W_2}, Y^{W_2})$.

Locally, these d -tensor fields can be written as

$$(6.2) \quad \begin{cases} \mathbb{G}^H = g_{ab}^{(0)} dx^a \otimes dx^b, & \mathbb{G}^{V_1} = g_{ab}^{(1)} \delta y^a \otimes \delta y^b, \\ \mathbb{G}^{W_2} = g^{ab} \delta p_a \otimes \delta p_b, & \end{cases}$$

where

$$(6.2') \quad g_{ab}^{(0)} = \mathbb{G}(\delta_a, \delta_b), \quad g_{ab}^{(1)} = \mathbb{G}(\dot{\partial}_a, \dot{\partial}_b), \quad g^{ab} = \mathbb{G}(\dot{\partial}^a, \dot{\partial}^b),$$

$$(6.3) \quad \text{rank} \parallel g_{ab}^{(\alpha)} \parallel = n, (\alpha = 0, 1, 2), \quad \parallel g_{ab}^{(2)} \parallel = \parallel g^{ab} \parallel^{-1}.$$

Thus the decomposition (6.1) looks locally as following:

$$(6.4) \quad \mathbb{G} = g_{ab}^{(0)} dx^a \otimes dx^b + g_{ab}^{(1)} \delta y^a \otimes \delta y^b + g^{ab} \delta p_a \otimes \delta p_b.$$

Definition 6.2 An N -linear connection D on $T^{*2}M$ endowed with a metric structure \mathbb{G} is said to be a metric \mathbf{N} -linear connection if $D_X \mathbb{G} = 0$ for every $X \in T^{*2}M$.

Let \mathbb{G} be a metric structure on $T^{*2}M$ given by (6.4)

We have

Proposition 6.2 An N -linear connection on $T^{*2}M$ is a metric N -linear connection with respect to \mathbb{G} given by (6.4) if and only if

$$(6.5) \quad g_{ab|c}^{(\alpha)} = 0, \quad g_{ab}^{(\alpha)} |_{\alpha c} = 0, \quad g^{ab} |^{\alpha c} = 0,$$

where $\parallel g^{ab} \parallel = \parallel g_{ab} \parallel^{-1}$, $(\alpha = 0, 1, 2)$.

Remark 6.1 The conditions (6.5) are equivalent with the conditions

$$(6.5') \quad g^{ab} |_{\alpha c} = 0, \quad g^{ab} |_{\alpha c} = 0, \quad g_{ab} |^{\alpha c} = 0, \quad (\alpha = 0, 1, 2).$$

We shall now discuss the existence of metric N -linear connection on $T^{*2}M$.

By a straightforward calculus we get

Theorem 6.1 *If the manifold T^*M is endowed with the metric structure \mathbb{G} given by (6.4), then there exists on $T^{*2}M$ a metric N -linear connection, depending only on \mathbb{G} . Its local coefficients:*

$$D\Gamma(N) := \left(\underset{(00)}{H^a}_{bc}, \underset{(10)}{H^a}_{bc}, \underset{(20)}{H^a}_{bc}, \underset{(01)}{C^a}_{bc}, \underset{(11)}{C^a}_{bc}, \underset{(21)}{C^a}_{bc}, \underset{(02)}{C^a}_{bc}, \underset{(12)}{C^a}_{bc}, \underset{(22)}{C^a}_{bc} \right),$$

are as follows

$$(6.6) \quad \begin{aligned} \underset{(00)}{\overset{c}{H}}^a_{bc} &= \frac{1}{2} g^{ad} \left(\underset{(0)}{\delta}_c g_{bd} + \underset{(0)}{\delta}_b g_{dc} - \underset{(0)}{\delta}_d g_{bc} \right), \\ \underset{(10)}{\overset{c}{H}}^a_{bc} &= \underset{(11)}{B^a}_{cb} + \frac{1}{2} g^{ad} \left(\underset{(1)}{\delta}_c g_{bd} - \underset{(11)}{B^f}_{cb} g_{fd} - \underset{(11)}{B^f}_{cd} g_{bf} \right), \\ \underset{(20)}{\overset{c}{H}}^a_{bc} &= -\underset{(22)}{B^a}_{bc} + \frac{1}{2} g^{ad} \left(\underset{(2)}{\delta}_c g_{bd} + \underset{(22)}{B^f}_{bc} g_{fd} + \underset{(22)}{B^f}_{dc} g_{bf} \right), \\ \underset{(01)}{\overset{c}{C}}^a_{bc} &= \frac{1}{2} g^{ad} \underset{(0)}{\dot{\partial}}_c g_{bd}, \\ \underset{(11)}{\overset{c}{C}}^a_{bc} &= \frac{1}{2} g^{ad} \left(\underset{(1)}{\dot{\partial}}_c g_{bd} + \underset{(1)}{\dot{\partial}}_b g_{dc} - \underset{(1)}{\dot{\partial}}_d g_{bc} \right), \\ \underset{(21)}{\overset{c}{C}}^a_{bc} &= \frac{1}{2} g^{ad} \underset{(2)}{\dot{\partial}}_c g_{bd}, \\ \underset{(02)}{\overset{c}{C}}^a{}_{bc} &= -\frac{1}{2} g_{ad} \underset{(0)}{\dot{\partial}}_c g^{bd}, \\ \underset{(12)}{\overset{c}{C}}^a{}_{bc} &= -\frac{1}{2} g_{ad} \underset{(1)}{\dot{\partial}}^c g^{bd}, \\ \underset{(22)}{\overset{c}{C}}^a{}_{bc} &= -\frac{1}{2} g_{ad} \left(\underset{(2)}{\dot{\partial}}^c g^{bd} + \underset{(2)}{\dot{\partial}}^b g^{dc} - \underset{(2)}{\dot{\partial}}^d g^{bc} \right). \end{aligned}$$

Definition 6.3 The metric N -linear connection given by (6.6) will be called the canonical N -linear connection associated with \mathbb{G} .

Let

$$D\Gamma^*(N) = \left(\underset{(00)}{H^*a}_{bc}, \underset{(10)}{H^*a}_{bc}, \underset{(20)}{H^*a}_{bc}, \underset{(01)}{C^*a}_{bc}, \underset{(11)}{C^*a}_{bc}, \underset{(21)}{C^*a}_{bc}, \underset{(02)}{C^*a}_{bc}, \underset{(12)}{C^*a}_{bc}, \underset{(22)}{C^*a}_{bc} \right)$$

be an N -linear connection on $T^{*2}M$ which is endowed with a metric structure \mathbb{G} .

If we denote by $\underset{*}{|}_{\alpha c}, \underset{*}{|}_{\alpha c}, \underset{*}{|}^{\alpha c}$ the $h_{\alpha-}, v_{1\alpha-}$ and $w_{2\alpha-}$ covariant derivations with respect to $D\Gamma^*(N)$, then by a direct calculation one checks that the N -linear con-

nection whose local coefficients are given by

$$(6.7) \quad \begin{aligned} H_{(\alpha 0)}^a{}_{bc} &= \overset{*}{H}_{(\alpha 0)}^a{}_{bc} + \frac{1}{2} g_{(\alpha)}^{ad} g_{(\alpha)db} \overset{*}{\alpha}^c, \\ C_{(\alpha 1)}^a{}_{bc} &= \overset{*}{C}_{(\alpha 1)}^a{}_{bc} + \frac{1}{2} g_{(\alpha)}^{ad} g_{(\alpha)db} \overset{*}{\alpha}^c, \\ C_{(\alpha 2)}^a{}_{bc} &= \overset{*}{C}_{(\alpha 2)}^a{}_{bc} - \frac{1}{2} g_{(\alpha)}^{ad} g_{(\alpha)db} \overset{*}{\alpha}^c. \end{aligned}$$

is a metrical N -linear connection .

This method of metrisation of an N -linear connection is called the Kawaguchi metrisation process, [1], [11].

Let us associate to \mathbb{G} the following operators of Obata type:

$$(6.8) \quad \overset{\alpha}{O}_{ab}^{cd} = \frac{1}{2} \left(\delta_a^c \delta_b^d - g_{(\alpha)ab} g_{(\alpha)cd} \right), \quad \overset{\alpha}{O}_{ab}^{cd} = \frac{1}{2} \left(\delta_a^c \delta_b^d + g_{(\alpha)ab} g_{(\alpha)cd} \right),$$

$(\alpha = 0, 1, 2).$

Theorem 6.2 *The set of all metric N -linear connections with respect to \mathbb{G} on the manifold $T^{*2}M$ is given by*

$$(6.9) \quad \begin{aligned} H_{(\alpha 0)}^a{}_{bc} &= \overset{c}{H}_{(\alpha 0)}^a{}_{bc} + \overset{\alpha}{O}_{1bd}^{fa} \overset{\alpha}{X}^d f_c, \\ C_{(\alpha 1)}^a{}_{bc} &= \overset{c}{C}_{(\alpha 1)}^a{}_{bc} + \overset{\alpha}{O}_{1bd}^{fa} \overset{\alpha}{Y}^d f_c, \\ C_{(\alpha 2)}^a{}_{bc} &= \overset{c}{C}_{(\alpha 2)}^a{}_{bc} + \overset{\alpha}{O}_{1fa}^{bd} \overset{\alpha}{Z}_d f_c, \end{aligned}$$

$(\alpha = 0, 1, 2),$

where $\left(\overset{c}{H}_{(\alpha 0)}^a{}_{bc}, \overset{c}{C}_{(\alpha 1)}^a{}_{bc}, \overset{c}{C}_{(\alpha 2)}^a{}_{bc} \right)$ is the canonical N -linear connection (6.6), $\overset{\alpha}{X}^a, \overset{\alpha}{Y}^a, \overset{\alpha}{Z}^a$ are arbitrary d -tensor fields of type $(1, 2)$ and $\overset{\alpha}{Z}_a{}^{bc}$ are arbitrary d -tensor fields of type $(2, 1)$.

For demonstration we can see V. Cruceanu, R. Miron [7], V. Oproiu [12], [13].

7 N -linear connections of Miron type on $T^{*2}M$

An important particular case of N -linear connection on $T^{*2}M$ is given by following definition.

Definition 7.1 An N -linear connection D on $T^{*2}M$ is called **MN**-linear connection (N -linear connection of Miron type) if:

- 1°. The 1-tangent structure J is absolute parallel with respect to D .
- 2°. The presymplectic structure θ is absolute parallel with respect to D .

By straightforward calcul we get

Theorem 7.1 *An MN-linear connection on $T^{*2}M$ is characterized by the coefficients $MD\Gamma(N)$ given by (4.2) where*

$$(7.1) \quad \begin{aligned} H_{(00)}^a{}_{bc} &= H_{(10)}^a{}_{bc} = H_{(20)}^a{}_{bc} =: H^a{}_{bc}, \\ C_{(01)}^a{}_{bc} &= C_{(11)}^a{}_{bc} = C_{(21)}^a{}_{bc} =: C^a{}_{bc}, \\ C_{(02)}^a{}_{b^c} &= C_{(12)}^a{}_{b^c} = C_{(22)}^a{}_{b^c} =: C^a{}_{b^c}. \end{aligned}$$

Also, we obtain

Proposition 7.1 *For any MN-linear connection $MD\Gamma(N) = (H^a{}_{bc}, C^a{}_{bc}, C_a{}^{bc})$ we have*

$$(7.2) \quad D_X \mathbb{F} = 0, \quad \forall X \in \chi(T^{*2}M).$$

Remark 7.1 1°. We have $\{MD\Gamma(N)\} \subset \{D\Gamma(N)\}$.

2°. For any MN-linear connection, the $h_{\alpha-}, v_{1\alpha-}$ and $w_{2\alpha-}$ -covariant derivatives, ($\alpha = 0, 1, 2$), one reduce to $h-, v_1-$ and w_2- covariant derivatives. Also “ ${}_{|\alpha c}$ ”, ($\alpha = 0, 1, 2$) one reduce to “ ${}_{|c}$ ” only, “ ${}_{|\alpha c}$ ”, ($\alpha = 0, 1, 2$) one reduce to “ ${}_{|c}$ ” and “ ${}_{|\alpha c}$ ”, ($\alpha = 0, 1, 2$) one reduce to “ ${}_{|c}$ ”, ($c = 1, \dots, n$), respectively.

Whole these correspond of Acad. R. Miron theory on the Hamilton spaces of higher order recently achieved (see R.Miron [9], [10]).

From this pharagraf we clearly see how the results of this paper generalize the works remarked before. To work with nine coefficients for a linear connection on $T^{*2}M$ (replaced three) is an advantage in the physical applications, because, the torsion, the curvature, remarkable identities, etc., are much more substantial (see [6]).

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