

BH-mean curvature in Randers spaces with anisotropically scaled metric

Vladimir Balan

Abstract. Within the framework of Randers (α, β) -Finsler spaces with anisotropically scaled metric, the volume element and the mean curvature of hypersurfaces are obtained, extending thus the corresponding results from [6, 4]. As a particular case, the mean curvature form of hypersurfaces in conformally deformed Randers spaces are derived.

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Key words: Finsler structure, Randers metric, conformal deformation, mean curvature, minimality PDE.

1 Introduction

Within the framework of Finsler submanifolds, significant advances have been obtained by Z. Shen ([12]) by deriving the Busemann - Hausdorff (BH) mean curvature of a Finsler submanifold. Further, for (α, β) -Finsler submanifolds with constant β -form, M.Souza, K. Tenenblat and J. Spruck ([15, 14]) and the author ([3, 5]) have investigated Randers minimal hypersurfaces, and constant mean curvature (and in particular, minimal) Kropina hypersurfaces, respectively.

We should note that, as alternative, a special attention has been devoted to the Holmes - Thompson (HT) approach ([1, 2]), substantial progress being provided by Q. He and Y.-B. Shen ([8, 9]) and recently by B.Y. Wu ([16, 17, 18]).

In the present work, we determine the the volume element and the BH-mean curvature of isometrically immersed hypersurfaces in Randers (α, β) -Finsler spaces with anisotropically scaled metric with bounded indicatrix. In particular, these lead to the explicit formulas for the BH-mean curvature form in conformally deformed Randers spaces, which extend the already known results ([6, 4, 13, 15, 14, 16, 17, 18]).

Let (M, F) and (\tilde{M}, \tilde{F}) be Finsler structures, and $\varphi : (M, F) \rightarrow (\tilde{M}, \tilde{F})$ be an isometric immersion, with F induced by \tilde{F} . Then the following result holds true:

Theorem 1.1. *The mean curvature of M is given by ([12], (57), p.563)]*

$$(1.1) \quad \tilde{H}_\varphi(X) = G^{-1} \left(G_{;x^i} - G_{;z_a^i z_b^j} \varphi_{;u^a u^b}^j - G_{;x^j z_a^i} \varphi_{;u^a}^j \right) X^i,$$

where lower indices stand for corresponding partial derivatives and:

- $(u^a, v^b)_{a,b \in \overline{1,n}}$ are local coordinates in TM ($\dim M = n$);
- $(x^i, y^j)_{i,j \in \overline{1,m}}$ are local coordinates in $T\tilde{M}$ ($\dim \tilde{M} = m$);
- z_a^i are the entries of the Jacobian matrix $[J(\varphi)] = \left(\frac{\partial \varphi^i}{\partial u^a} \right)_{a=\overline{1,n}, i=\overline{1,m}}$;
- $\varphi_t : M \rightarrow \tilde{M}, t \in (-\varepsilon, \varepsilon), \varphi_0 = \varphi$, is the variation of the surface;
- X is the variation vector field $X_x = \left. \frac{\partial \varphi_t}{\partial t} \right|_{t=0} (x), \forall x \in M$;
- G is the coefficient of the induced Finsler volume form

$$(1.2) \quad G(z) = \frac{\text{vol}[B^n]}{\text{vol}\{(v^a) \in \mathbb{R}^n \mid \tilde{F}(v^a z_a^i \tilde{e}_i) \leq 1\}},$$

where $z = (z_a^i)_{a=\overline{1,n}, i=\overline{1,m}} \in GL_{m \times n}(\mathbb{R})$, $\tilde{e} = \{\tilde{e}_i\}_{i=\overline{1,m}}$ is an arbitrary basis in \mathbb{R}^m and $B^n \subset \mathbb{R}^n$ is the standard Euclidean ball.

It has been shown ([12]) that the variation of the volume of M reaches a minimum for $\tilde{H}_\varphi = 0$.

2 The scaled Randers case

We shall further obtain the explicit formulas for the mean curvature form in the scaled Randers case, which extends the known free-potential case ([6, 4]).

In the following we consider the Finsler hypersurfaces ($\dim \tilde{M} = m = n + 1$) for the scaled Randers structure ([11, 7, 10]) with the fundamental function

$$(2.1) \quad \tilde{F}(x, y) = \left(\sum_{i=1}^{n+1} a_i^2(x) (y^i)^2 \right)^{1/2} + a_{n+1}(x) b_{n+1}(x) y^{n+1},$$

with $b_{n+1}(x) \in [0, 1)$ and a_1, \dots, a_{n+1} positive functions of x . We note that for $a_1 = \dots = a_{n+1} = 1$ this metric reduces to the case studied in [6, 4] and further, for $b_{n+1} = \text{const.}$, to the one studied by M. Souza, K. Tenenblat and J. Spruck ([15, 14]).

Let $M = \text{Im } \varphi$, $\varphi : D \subset \mathbb{R}^n \rightarrow \tilde{M} = \mathbb{R}^{n+1}$ be a isometrically imbedded simple hypersurface. We denote the Jacobian entries by $z_\alpha^i = \frac{\partial \varphi^i}{\partial u^\alpha}$, $u = (u^1, \dots, u^n) \in D$. We shall further use the notations:

$$\begin{cases} C = \sqrt{\det(h_{\alpha\beta})}, \text{ where } h_{\alpha\beta} = \sum_{i=1}^{n+1} z_\alpha^i z_\beta^i \\ \tilde{C} = \sqrt{\det(\tilde{h}_{\alpha\beta})}, \text{ where } \tilde{h}_{\alpha\beta} = \sum_{i=1}^{n+1} \tilde{z}_\alpha^i \tilde{z}_\beta^i, \end{cases}$$

with $\tilde{z}_\alpha^i = a_i z_\alpha^i$ (with no summation after i), and

$$B = b^2 z_\alpha^{n+1} z_\beta^{n+1} h^{\alpha\beta}, \quad \tilde{B} = b^2 z_\alpha^{n+1} \tilde{z}_\beta^{n+1} \tilde{h}^{\alpha\beta}.$$

Then, using

$$\begin{aligned}\Delta = \det(g_{\alpha\beta}) &\Rightarrow \frac{\partial\sqrt{\Delta}}{\partial\tau} = \frac{\sqrt{\Delta}}{2}g^{\alpha\beta}\frac{\partial g_{\alpha\beta}}{\partial\tau} \\ g_{\alpha\beta}g^{\beta\gamma} = \delta_\alpha^\gamma &\Rightarrow \frac{\partial g^{\alpha\beta}}{\partial\tau} = -g^{\alpha\gamma}g^{\beta\delta}\frac{\partial g_{\gamma\delta}}{\partial\tau}\end{aligned}$$

we easily infer that denoting $\tilde{C}_{x^i} = \frac{\partial\tilde{C}}{\partial x^i}$, $\tilde{B}_{*i} = b^2\frac{\partial}{\partial x^i}(\tilde{z}_\alpha^{n+1}\tilde{z}_\beta^{n+1}\tilde{h}^{\alpha\beta})$, we get

$$\begin{cases} \tilde{C}_{x^i} = \tilde{C} \cdot \tilde{h}^{\alpha\beta} \sum_{j=1}^{n+1} \tilde{z}_\alpha^j \tilde{z}_\beta^j \theta_{j,i} \\ \tilde{B}_{*i} = 2 \left(\tilde{B} \theta_{n+1,i} - b^2 \tilde{z}_\alpha^{n+1} \tilde{z}_\beta^{n+1} \tilde{h}^{\alpha\gamma} \tilde{h}^{\beta\delta} \sum_{j=1}^{n+1} \tilde{z}_\gamma^j \tilde{z}_\delta^j \theta_{j,i} \right) \end{cases}$$

where $\theta_{j,i} = \frac{\partial \ln a_i}{\partial x^i}$. Then, applying the previous Theorem and the expression of the induced volume density for hypersurfaces $\tilde{G} = \tilde{C} \cdot (1 - \tilde{B})^{(n+1)/2}$ in Randers spaces, we obtain the following result:

Theorem 2.1. *The components of the mean curvature 1-form of the hypersurface M , isometrically immersed in the Randers space $\tilde{M} = \mathbb{R}^{n+1}$ endowed with the fundamental function (2.1), are given by*

$$(2.2) \quad \tilde{H}_i = H_i + H_{*i}, \quad i = \overline{1, n+1}$$

with

$$(2.3) \quad \begin{aligned} H_i &= -\frac{(n+1)\tilde{B}\omega_i}{1-\tilde{B}} - \frac{1}{\tilde{C}} \cdot \left[\frac{(n^2-1)}{4(1-\tilde{B})^2} \frac{\partial\tilde{B}}{\partial z_\varepsilon^i} \frac{\partial\tilde{B}}{\partial z_\eta^j} \tilde{C} + \frac{\partial^2\tilde{C}}{\partial z_\varepsilon^i \partial z_\eta^j} - \right. \\ &\quad \left. - \frac{n+1}{2(1-\tilde{B})} \cdot \left(\frac{\partial^2\tilde{B}}{\partial z_\varepsilon^i \partial z_\eta^j} \tilde{C} + \frac{\partial\tilde{B}}{\partial z_\eta^j} \frac{\partial\tilde{C}}{\partial z_\varepsilon^i} + \frac{\partial\tilde{B}}{\partial z_\varepsilon^i} \frac{\partial\tilde{C}}{\partial z_\eta^j} \right) \right] \varphi_{\varepsilon\eta}^j + \\ &\quad + \frac{(n+1)\omega_j}{\tilde{C}(1-\tilde{B})} \left[\tilde{B} \frac{\partial\tilde{C}}{\partial z_\varepsilon^i} + \left(1 - \frac{\tilde{B}(n-1)}{2(1-\tilde{B})} \right) \tilde{C} B_{z_\varepsilon^i} \right] \cdot \frac{\partial\varphi^j}{\partial u^\varepsilon}, \\ H_{*i} &= \frac{\tilde{C}_{x^i}}{\tilde{C}} - \frac{n+1}{2(1-\tilde{B})} \tilde{B}_{*i} - \left[\frac{\tilde{C}_{x^i z_\alpha^i}}{\tilde{C}} - \frac{n+1}{2(1-\tilde{B})} \left(\tilde{C}_{x^j} \cdot \tilde{B}_{z_\alpha^i} \cdot \frac{1}{\tilde{C}} + \right. \right. \\ &\quad \left. \left. + \tilde{C}_{z_\alpha^i} \tilde{B}_{x^j} \cdot \frac{1}{\tilde{C}} - \frac{n-1}{2(1-\tilde{B})} \tilde{B}_{z_\alpha^i} \tilde{B}_{*j} + \frac{\partial}{\partial z_\alpha^i} \tilde{B}_{*j} \right) \right] \varphi_\alpha^j, \end{aligned}$$

where $\omega_i = \partial \ln b / \partial x^i$, $\varphi_{\varepsilon\eta}^j = \frac{\partial^2 \varphi^j}{\partial u^\varepsilon \partial u^\eta}$ and $\varphi_\varepsilon^j = \frac{\partial \varphi^j}{\partial u^\varepsilon}$.

Proof. We have

$$\tilde{G}_{x^i} = -(n+1)\tilde{B}\tilde{C}(1-\tilde{B})^{(n-1)/2} \cdot \omega_i + \tilde{G}_{*i},$$

where $\tilde{G}_{*i} = \tilde{C}_{x^i}(1-\tilde{B})^{(n+1)/2} - \frac{n+1}{2}\tilde{C}(1-\tilde{B})^{(n-1)/2}\tilde{B}_{*i}$ and

$$\tilde{G}_{x^j z_\alpha^i} = \frac{\partial}{\partial z_\alpha^i} \left(-(n+1)\tilde{B}\tilde{C}(1-\tilde{B})^{(n-1)/2} \cdot \omega_i \right) + \tilde{G}_{*ji\alpha},$$

with

$$\begin{aligned} \tilde{G}_{*ji\alpha} = & \tilde{C}_{x^j z_\alpha^i} (1-\tilde{B})^{(n+1)/2} - \frac{(n+1)(1-\tilde{B})^{(n-1)/2}}{2} \\ & \cdot \left[\tilde{C}_{x^j} \tilde{B}_{z_\alpha^i} + \tilde{C}_{z_\alpha^i} \tilde{B}_{*j} - \frac{n-1}{2(1-\tilde{B})} \tilde{C} \tilde{B}_{z_\alpha^i} \tilde{B}_{*j} + \frac{\partial}{\partial z_\alpha^i} \tilde{B}_{*j} \right]. \end{aligned}$$

Further, using (1.1), the claim follows. \square

3 The conformally deformed Randers case

As a particular case, for $a_1(x) = \dots = a_{n+1}(x) = a(x) = e^{\sigma(x)}$, the previous theorem provides the mean curvature for the homothetic (conformal) deformation of the Finsler metric investigated in [4, 6], as follows

Corollary 3.1. *The components of the mean curvature 1-form of the hypersurface M , isometrically immersed in the Randers space $\tilde{M} = \mathbb{R}^{n+1}$ endowed with the fundamental function*

$$(3.1) \quad \tilde{F}(x, y) = a(x) \cdot \left[\left(\sum_{i=1}^{n+1} (y^i)^2 \right)^{1/2} + b_{n+1}(x) y^{n+1} \right],$$

are given by

$$(3.2) \quad \tilde{H}_i = H_i + H_{*i}, \quad i = \overline{1, n+1}$$

with

$$\begin{aligned} (3.3) \quad H_i = & -\frac{(n+1)B\omega_i}{1-B} - \frac{1}{C} \cdot \left[\frac{(n^2-1)}{4(1-B)^2} B_{z_\varepsilon^i} B_{z_\eta^j} C + \right. \\ & \left. + C_{z_\varepsilon^i z_\eta^j} - \frac{n+1}{2(1-B)} \cdot \left(B_{z_\varepsilon^i z_\eta^j} C + B_{z_\eta^j} C_{z_\varepsilon^i} + B_{z_\varepsilon^i} C_{z_\eta^j} \right) \right] \varphi_{\varepsilon\eta}^j + \\ & + \frac{(n+1)\omega_j}{C(1-B)} \left[B C_{z_\varepsilon^i} + \left(1 - \frac{B(n-1)}{2(1-B)} \right) C B_{z_\varepsilon^i} \right] \cdot \frac{\partial \varphi^j}{\partial u^\varepsilon}, \\ H_{*i} = & \frac{n}{2} \left[\theta_i - \left(\frac{1}{C} C_{z_\alpha^i} - \frac{n+1}{2(1-B)} B_{z_\alpha^i} \right) \theta_j \varphi_\alpha^j \right], \end{aligned}$$

where $\omega_i = \partial \ln b / \partial x^i$, $\theta_i = \frac{\partial \sigma}{\partial x^i}$, $\varphi_{\varepsilon\eta}^j = \frac{\partial^2 \varphi^j}{\partial u^\varepsilon \partial u^\eta}$ and $\varphi_\varepsilon^j = \frac{\partial \varphi^j}{\partial u^\varepsilon}$.

Proof. Denoting $a = e^{\sigma(x)}$ and $\theta_i = \frac{\partial \ln a}{\partial x^i} = \frac{\partial \sigma}{\partial x^i}$, we use the relations: $\tilde{h}_{\alpha\beta} = a^2 h_{\alpha\beta}$, $\tilde{h}^{\alpha\beta} = a^{-2} h^{\alpha\beta}$, $\tilde{B} = B$, $\tilde{C} = a^n C$, $\tilde{C}_{z_\alpha^i} = a^n C_{z_\alpha^i}$, $\tilde{C}_{x^i} = n\theta_i \tilde{C}$, $\tilde{C}_{x^j z_\alpha^i} = n\theta_j \tilde{C}_{z_\alpha^i}$. \square

Corollary 3.2. *The two constituents of the mean curvature 1-form (3.2) rewrite in terms of C and $E = BC^2$ as follows:*

$$\begin{aligned}
(3.4) \quad H_i &= -\frac{1}{C(C^2 - E)} \left[(C^2)_{z_\varepsilon^i z_\eta^j} \cdot k_{c_2} - E_{z_\varepsilon^i z_\eta^j} \cdot k_{e_2} + E_{z_\varepsilon^i} E_{z_\eta^j} \cdot k_{e_{12}} + \right. \\
&\quad \left. + \left(C_{z_\varepsilon^i} E_{z_\eta^j} + C_{z_\eta^j} E_{z_\varepsilon^i} \right) \cdot k_{ce} + C_{z_\varepsilon^i} C_{z_\eta^j} \cdot k_{cc} \right] \varphi_{\varepsilon\eta}^j + \\
&\quad + \frac{(n+1)}{C(C^2 - E)} \left[EC_{z_\varepsilon^i} + k_m \cdot (CE_{z_\varepsilon^i} - 2EC_{z_\varepsilon^i}) \right] \omega_j \varphi_\varepsilon^j - \frac{(n+1)E}{C^2 - E} \omega_i, \\
H_{*i} &= \frac{n}{2} \left[\theta_i + \frac{1}{C^2 - E} \left(\frac{n+1}{2} E_{z_\alpha^i} - \frac{C^2 + nE}{C} C_{z_\alpha^i} \right) \theta_j \varphi_\alpha^j \right]
\end{aligned}$$

where

$$\begin{aligned}
k_{e_2} &= \frac{(n+1)C}{2}, \quad k_{e_{12}} = \frac{(n^2 - 1)C}{4(C^2 - E)}, \quad k_{ce} = \frac{(n+1)(C^2 - nE)}{2(C^2 - E)}, \\
k_{c_2} &= \frac{C^2 + nE}{2C}, \quad k_{cc} = \frac{n(n+2)E^2 - 2nEC^2 - C^4}{C(C^2 - E)}, \quad k_m = 1 - \frac{(n-1)E}{2(C^2 - E)}
\end{aligned}$$

Remark 3.3. a) We note that for $a(x) \equiv 1$, one obtains the case of nonconstant potential studied in [6, 4]. Moreover, for $b = \text{const.}$ (i.e., for $\omega_i = 0$, $\forall i \in \overline{1, n+1}$), $H_i X^i = 0$ leads to the minimality characterization obtained by Souza-Tenenblat ([15, Theorem 2, p. 629]).

b) For $n = 2, b_{n+1} \equiv 0, a \equiv 1$ and $\varphi(u, v) = (u, v, f(u, v))$, $X = \varphi_u \times \varphi_v$, (3.1) becomes the Euclidean norm, and the equation $H_i X^i = 0$ becomes the classical minimal surface equation

$$(1 + f_u^2) f_{vv} - 2f_u f_v f_{uv} + (1 + f_v^2) f_{uu} = 0.$$

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Author's address:

Vladimir Balan
University Politehnica of Bucharest, Faculty of Applied Sciences,
Department of Mathematics I, Splaiul Independentei 313,
RO-060042, Bucharest, Romania.
E-mail address: vbalan@mathem.pub.ro