

Nonholonomic Gibbs hypersurface

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*Dedicated to the 70-th anniversary
of Professor Constantin Udriște*

Abstract. The paper presents three different geometries of the Gibbs nonholonomic hypersurface: Vranceanu geometry (Section 2), Dobrescu-Stamin-Udriște geometry (Section 3) and Udriște-Dogaru geometry (Section 4). All require to introduce the first and the second fundamental forms, and to use the derived geometrical objects. The main results include: the scalar curvature of Gibbs-Vranceanu nonholonomic hypersurface reflects a saddle behavior, the Gibbs-Dobrescu-Stamin-Udriște nonholonomic hypersurface has positive Gauss-Kronecker curvature and vanishing mean curvature, the Gibbs-Udriște-Dogaru nonholonomic hypersurface has a rational scalar curvature.

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1 Gibbs contact structure

The Gibbs contact structure means the triplet

$$(\mathbf{R}^5, \delta_{ab}, \theta), \mathbf{R}^5 = \{(U, T, S, P, V)\}, \theta = dU - TdS + PdV,$$

where we preserve the names U - *internal energy*, S - *entropy*, T - *temperature*, V - *volume* and P - *pressure* for the independent variables, but none is restricted to positive values as in thermodynamics.

2 Gibbs-Vranceanu nonholonomic hypersurface

The nonholonomic spaces submersed into a Riemannian space has been introduced by Vranceanu ([7]) and independently by Horak ([2]) in 1927, with the purpose to obtain a geometric interpretation of nonholonomic mechanical systems.

Here, we follow the theory of nonholonomic subspaces, as it is exposed in [7], [6]. The Gibbs-Vranceanu (GV) hypersurface is defined by the Pfaff equation

$$V_5^4 : dU - TdS + PdV = 0$$

and by a co-frame that will be introduced in this Section. For mathematical convenience, we denote the coordinates by

$$(2.1) \quad x^1 = T, \quad x^2 = S, \quad x^3 = P, \quad x^4 = V, \quad x^5 = U$$

and rewrite the GV equation as

$$V_5^4 : ds^5 = dx^5 - x^1 dx^2 + x^3 dx^4 = 0.$$

The transformation group of V_5^4 is given by the following formula

$$(2.2) \quad \begin{aligned} d\bar{s}^h &= c_k^h ds^k + c_5^h ds^5, \quad (h, k = \overline{1,4}) \\ d\bar{s}^5 &= c_5^5 ds^5, \\ c_k^5 &= 0, \quad c_k^h c_l^h = \delta_l^k, \quad c_5^5 = 1. \end{aligned}$$

The intrinsic invariants of nonholonomic hypersurface V_5^4 are ([6], p. 243-244): the *Gibbs-Pfaff equation*

$$(2.3) \quad ds^5 = 0$$

and the *Riemannian metric*

$$(2.4) \quad \varphi = (ds^1)^2 + (ds^2)^2 + (ds^3)^2 + (ds^4)^2 \pmod{(ds^5)}.$$

The equation (2.3) can be written

$$(2.5) \quad dx^5 + a_i^5 dx^i = 0, \quad (i = \overline{1,4}).$$

Thus, by a transformation

$$d\bar{s}^h = ds^h + c_5^h ds^5, \quad h = \overline{1,4}, i = \overline{1,4},$$

of the group (2.2), we get

$$d\bar{s}^h = \lambda_i^h dx^i + \lambda_5^h dx^5 + c_5^h (dx^5 + a_i^5 dx^i).$$

Choosing $c_5^h = -\lambda_5^h$, one can suppose that

$$(2.6) \quad ds^h = (\lambda_i^h - \lambda_5^h a_i^5) dx^i, \quad h = \overline{1,4}.$$

Being given the Riemannian metric $ds^2 = \delta_{ab} ds^a ds^b$ of the space \mathbb{R}^5 and the equation $ds^5 = dx^5 + \lambda_i^5 dx^i = 0$, $i = \overline{1,4}$, the induced Riemannian metric of $V_5^4 : ds^5 = 0$ is completely determined

$$ds^2 = \delta_{\alpha\beta} ds^\alpha ds^\beta, \quad \alpha, \beta = \overline{1,4},$$

$$(2.7) \quad \begin{aligned} ds^2 &= \delta_{\alpha\beta} \lambda_i^\alpha \lambda_j^\beta dx^i dx^j \\ &= \delta_{\alpha\beta} \lambda_\gamma^\alpha \lambda_\eta^\beta dx^\gamma dx^\eta + 2\delta_{\alpha\beta} \lambda_5^\alpha \lambda_\gamma^\beta dx^5 dx^\gamma + \delta_{\alpha\beta} \lambda_5^\alpha \lambda_5^\beta dx^5 dx^5 \\ &= \delta_{\alpha\beta} \lambda_\gamma^\alpha \lambda_\eta^\beta dx^\gamma dx^\eta + 2\delta_{\alpha\beta} \lambda_5^\alpha \lambda_\gamma^\beta (-\lambda_\varepsilon^5 dx^\varepsilon) dx^\gamma + \\ &\quad + \delta_{\alpha\beta} \lambda_5^\alpha \lambda_5^\beta (-\lambda_\varepsilon^5 dx^\varepsilon) (-\lambda_5^5 dx^5) \\ &= \left(\delta_{\alpha\beta} \lambda_\gamma^\alpha \lambda_\eta^\beta - 2\delta_{\alpha\beta} \lambda_5^\alpha \lambda_\gamma^\beta \lambda_\eta^5 + \delta_{\alpha\beta} \lambda_5^\alpha \lambda_5^\beta \lambda_\eta^5 \lambda_\gamma^5 \right) dx^\gamma dx^\eta. \end{aligned}$$

To introduce a suitable co-frame, we select the 1-forms 2.6 as

$$\begin{aligned} ds^1 &= x^1 dx^2, \\ ds^2 &= x^3 dx^4, \\ ds^3 &= dx^5 + x^4 dx^3 + x^3 dx^4, \\ ds^4 &= dx^5 - x^2 dx^1 - x^1 dx^2, \end{aligned}$$

or in matrix language

$$\lambda = \begin{pmatrix} 0 & x^1 & 0 & 0 \\ 0 & 0 & 0 & x^3 \\ 0 & x^1 & x^4 & 0 \\ -x^2 & 0 & 0 & -x^3 \end{pmatrix}.$$

Then the Riemannian metric of the nonholonomic hypersurface V_5^4 is

$$\begin{aligned} ds^2 &= (ds^1)^2 + (ds^2)^2 + (ds^3)^2 + (ds^4)^2 \stackrel{ds^5=0}{=} \\ &= (x^1 dx^2)^2 + (x^3 dx^4)^2 + (x^1 dx^2 + x^4 dx^3)^2 + (x^3 dx^4 + x^2 dx^1)^2 \\ &= x^2 dx^1^2 + 2x^1 dx^2^2 + x^4 dx^3^2 + 2x^3 dx^4^2 + 2x^1 x^4 dx^2 dx^3 + \\ &\quad + 2x^2 x^3 dx^1 dx^4 \\ &= g_{ij} dx^i dx^j, \quad i, j = \overline{1, 4}, \end{aligned}$$

$$(g_{ij}) = \begin{pmatrix} x^2 & 0 & 0 & x^2 x^3 \\ 0 & 2x^1 & x^1 x^4 & 0 \\ 0 & x^1 x^4 & x^4 & 0 \\ x^2 x^3 & 0 & 0 & 2x^3 \end{pmatrix}.$$

If we operate the substitutions (2.1), we recognize that the components g_{ij} , $i, j = \overline{1, 4}$ are the *thermodynamic energies* T^2 , S^2 , P^2 , V^2 , TV , SP .

Reciprocally, starting from the Riemannian metric (g_{ij}) , $i, j = \overline{1, 4}$, of $V_5^4 : ds^5 = 0$, we can build an infinity of Riemannian metrics of \mathbb{R}^5 ,

$$\begin{aligned} ds^2 &= g_{ij} dx^i dx^j + 2g_{i5} dx^i ds^5 + g_{55} (ds^5)^2 \\ &= x^2 dx^1^2 + 2x^1 dx^2^2 + x^4 dx^3^2 + 2x^3 dx^4^2 + 2x^1 x^4 dx^2 dx^3 + \\ &\quad + 2x^2 x^3 dx^1 dx^4 + 2g_{i5} dx^i (dx^5 - x^1 dx^2 + x^3 dx^4) + \\ &\quad + g_{55} (dx^5 - x^1 dx^2 + x^3 dx^4)^2, \end{aligned}$$

where $g_{i5}, g_{55} : \mathbb{R}^5 \rightarrow R$ are arbitrary C^∞ functions.

Taking now the Lagrange function

$$L = \frac{1}{2} \left(g_{ij} \frac{dx^i}{dt} \frac{dx^j}{dt} + 2g_{i5} \frac{dx^i}{dt} \frac{ds^5}{dt} + g_{55} \frac{ds^5}{dt} \frac{ds^5}{dt} \right),$$

on $\mathbb{R} \times \mathbb{R}^5 \times \mathbb{R}^5$, where $g_{ij} = \delta_{hk} \lambda_i^h \lambda_j^k$, the equations of the geodesics of the space $V_5^4 : ds^5 = dx^5 + \lambda_i^5 dx^i = 0$ (the Euler-Lagrange equations induced on $V_5^4 : ds^5 = 0$)

are

$$\begin{aligned} \frac{d}{dt} \left(g_{ij} \frac{dx^j}{dt} + g_{j5} \frac{dx^j}{dt} \lambda_i^5 \right) - \frac{1}{2} \frac{\partial g_{jk}}{\partial x^i} \frac{dx^j}{dt} \frac{dx^k}{dt} - g_{j5} \frac{dx^j}{dt} \frac{\partial \lambda_k^5}{\partial x^i} \frac{dx^k}{dt} &= 0, \\ \frac{d}{dt} \left(g_{i5} \frac{dx^i}{dt} \right) - \frac{1}{2} \frac{\partial g_{jk}}{\partial x^5} \frac{dx^j}{dt} \frac{dx^k}{dt} - g_{j5} \frac{dx^j}{dt} \frac{\partial \lambda_k^5}{\partial x^5} \frac{dx^k}{dt} &= 0. \end{aligned}$$

Using the second order Christoffel symbols

$$\Gamma_{jk}^i = \frac{1}{2} g^{il} \left(\frac{\partial g_{kl}}{\partial x^j} + \frac{\partial g_{jl}}{\partial x^k} - \frac{\partial g_{jk}}{\partial x^l} \right),$$

we compute the Riemannian tensor

$$R_{jkl}^i = \Gamma_{jl,k}^i - \Gamma_{jk,l}^i + \Gamma_{jl}^m \Gamma_{mk}^i - \Gamma_{jk}^m \Gamma_{ml}^i, \quad i, j, k, l = \overline{1,4},$$

where the comma indicates the derivation with respect to the variable whose index follows the comma ([3]). Finally, the Ricci tensor has the components $R_{jl} = R_{jl}^i$ explicitly given by

$$\begin{aligned} R_{11} &= -\frac{x^2(x^1x^2+2x^3x^4)}{x^1x^3x^4}, \\ R_{12} = R_{21} &= \frac{30x^3x^4+6x^1x^2x^3x^4+2x^1x^2x^2}{2x^1x^2x^3x^4}, \\ R_{13} = R_{31} &= \frac{(x^1x^2+x^3x^4)^2}{6x^1x^2x^3x^4}, \\ R_{14} = R_{41} &= -\frac{2x^3x^4+7x^1x^2x^3x^4+4x^1x^2x^2}{2x^1x^2x^3x^4}, \\ R_{22} &= -\frac{3x^3x^4+8x^1x^2x^3x^4+2x^1x^2x^2}{2x^2x^3x^4}, \\ R_{23} = R_{32} &= -\frac{4x^3x^4+7x^1x^2x^3x^4+2x^1x^2x^2}{2x^1x^2x^3x^4}, \\ R_{24} = R_{42} &= \frac{4x^3x^4+7x^1x^2x^3x^4+4x^1x^2x^2}{2x^1x^2x^3x^4}, \\ R_{33} &= -\frac{x^4(2x^1x^2+x^3x^4)}{x^1x^2x^3}, \\ R_{34} = R_{43} &= \frac{2x^3x^4+6x^1x^2x^3x^4+3x^1x^2x^2}{2x^1x^2x^3x^4}, \\ R_{44} &= -\frac{2x^3x^4+8x^1x^2x^3x^4+3x^1x^2x^2}{2x^1x^2x^4}. \end{aligned}$$

The scalar curvature

$$c = g^{ij} R_{ij}, \quad c = \frac{3x^3x^4 + 3x^1x^2x^2 - 4x^1x^2x^3x^4}{2x^1x^2x^3x^4}$$

reflects a saddle behavior.

3 Gibbs-Dobrescu-Stamin-Udriște noholonomic hypersurface

Consider again the nonholonomic hypersurface described by the Pfaff equation

$$E_5^4 : dx^5 - x^1 dx^2 + x^3 dx^4 = 0,$$

in the notations (2.1). To apply the congruences method, as it is described in [1] (p. 398-403), we use the equivalent equation (no singular point)

$$ds^5 = \frac{1}{Q}dx^5 - \frac{x^1}{Q}dx^2 + \frac{x^3}{Q}dx^4 = 0, \quad Q = \sqrt{1 + x^{1^2} + x^{3^3}}.$$

We add now our co-frame, by associating the Pfaff forms

$$\begin{aligned} ds^1 &= TdS, \\ ds^2 &= PdV, \\ ds^3 &= dU + VdP + PdV, \\ ds^4 &= dU - SdT - TdS, \end{aligned}$$

whose thermodynamic sense is obvious. In general notations, we have

$$\begin{aligned} ds^1 &= x^1 dx^2, \\ ds^2 &= x^3 dx^4, \\ ds^3 &= dx^5 + x^4 dx^3 + x^3 dx^4, \\ ds^4 &= dx^5 - x^2 dx^1 - x^1 dx^2, \end{aligned}$$

with the associated matrix

$$\lambda = \begin{pmatrix} 0 & x^1 & 0 & 0 & 0 \\ 0 & 0 & 0 & x^3 & 0 \\ 0 & 0 & x^4 & x^3 & 1 \\ -x^2 & -x^1 & 0 & 0 & 1 \\ 0 & -\frac{x^1}{Q} & 0 & \frac{x^3}{Q} & \frac{1}{Q} \end{pmatrix}$$

and its inverse

$$\mu = \begin{pmatrix} 0 & -\frac{1}{x^2} & 0 & -\frac{1}{x^2} & \frac{Q}{x^2} \\ \frac{1}{x^1} & 0 & 0 & 0 & 0 \\ -\frac{1}{x^4} & 0 & \frac{1}{x^4} & 0 & -\frac{Q}{x^4} \\ 0 & \frac{1}{x^3} & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & Q \end{pmatrix}.$$

The first fundamental form of the nonholonomic hypersurface E_5^4 ([1], p. 401) is given by

$$I = ds^2 = \delta_{ij} dx^i dx^j = E_{\alpha\beta} ds^\alpha ds^\beta, \quad E_{\alpha\beta} = \delta_{ij} \mu_\alpha^i \mu_\beta^j, \quad i, j = \overline{1, 5}, \quad \alpha, \beta = \overline{1, 4}.$$

Explicitly,

$$E_{\alpha\beta} = \begin{pmatrix} \frac{1}{x^{1^2}} + \frac{1}{x^{4^2}} + 1 & -1 & -\frac{1}{x^{4^2}} & 0 \\ -1 & \frac{1}{x^{2^2}} + \frac{1}{x^{3^2}} + 1 & 0 & \frac{1}{x^{2^2}} \\ -\frac{1}{x^{4^2}} & 0 & \frac{1}{x^{4^2}} & 0 \\ 0 & \frac{1}{x^{2^2}} & 0 & \frac{1}{x^{2^2}} \end{pmatrix},$$

respectively

$$\begin{aligned} ds^2 &= \left(\frac{1}{x^{1^2}} + \frac{1}{x^{4^2}} + 1 \right) (ds^1)^2 + \left(\frac{1}{x^{2^2}} + \frac{1}{x^{3^2}} + 1 \right) (ds^2)^2 + \frac{1}{x^{4^2}} (ds^3)^2 + \\ &+ \frac{1}{x^{2^2}} (ds^4)^2 - ds^1 ds^2 - \frac{2}{x^{4^2}} ds^1 ds^3 + \frac{2}{x^{2^2}} ds^2 ds^4. \end{aligned}$$

The second fundamental form of the nonholonomic hypersurface E_5^4 ([1], p. 403) is

$$II = D_{\alpha\beta} ds^\alpha ds^\beta, \quad D_{\alpha\beta} = -\frac{\partial \lambda_i^5}{\partial x^j} \mu_\alpha^i \mu_\beta^j, \quad i, j = \overline{1, 5}, \quad \alpha, \beta = \overline{1, 4}.$$

We obtain

$$D_{\alpha\beta} = \begin{pmatrix} 0 & -\frac{1}{x^1 x^2 Q} & 0 & -\frac{1}{x^1 x^2 Q} \\ \frac{1}{x^3 x^4 Q} & 0 & -\frac{1}{x^3 x^4 Q} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

and thus

$$II = -\frac{1}{x^1 x^2 x^3 x^4 Q} [(x^3 x^4 - x^1 x^2) ds^1 ds^2 - x^3 x^4 ds^1 ds^4 + x^1 x^2 ds^2 ds^3].$$

The symmetric part is

$$\begin{aligned} D_{\alpha\beta}^s &= \frac{D_{\alpha\beta} + D_{\beta\alpha}}{2} = \\ &= \begin{pmatrix} 0 & \frac{1}{4Qx^3x^4} - \frac{1}{2Qx^1x^2} & 0 & -\frac{1}{2Qx^1x^2} \\ \frac{1}{2Qx^3x^4} - \frac{1}{4Qx^1x^2} & 0 & -\frac{1}{2Qx^3x^4} & 0 \\ 0 & -\frac{1}{4Qx^3x^4} & 0 & 0 \\ -\frac{1}{4Qx^1x^2} & 0 & 0 & 0 \end{pmatrix}, \end{aligned}$$

and

$$II_s = -\frac{(3x^3x^4 - 3x^1x^2) dx^1 dx^2 + x^3x^4 dx^1 dx^3 + 3x^1x^2 dx^2 dx^3 + 2x^3x^4 dx^1 dx^4}{4Qx^1x^2x^3x^4}.$$

The curvature of normal section, tangent to a curve C of the nonholonomic hypersurface, is given by ([1], p. 403):

$$\frac{1}{\rho} = \frac{D_{\alpha\beta} ds^\alpha ds^\beta}{E_{\alpha\beta} ds^\alpha ds^\beta}.$$

It follows the *Gauss-Kronecker curvature*

$$K = \frac{\det II_s}{\det I} = \frac{1}{64Q^4 (x_1^2 + x_3^2 + 1)} > 0$$

and the mean curvature $H = 0$. The nonholonomic hypersurface E_5^4 has no umbilical point since the system

$$\begin{aligned} &\frac{E_{11}}{D_{11}^s} = \frac{E_{22}}{D_{22}^s} = \frac{E_{33}}{D_{33}^s} = \frac{E_{44}}{D_{44}^s} = \\ &= \frac{E_{12}}{D_{12}^s} = \frac{E_{13}}{D_{13}^s} = \frac{E_{14}}{D_{14}^s} = \frac{E_{21}}{D_{21}^s} = \frac{E_{23}}{D_{23}^s} = \frac{E_{24}}{D_{24}^s} \\ &= \frac{E_{31}}{D_{31}^s} = \frac{E_{32}}{D_{32}^s} = \frac{E_{34}}{D_{34}^s} = \frac{E_{41}}{D_{41}^s} = \frac{E_{42}}{D_{42}^s} = \frac{E_{43}}{D_{43}^s}, \end{aligned}$$

has no solution.

4 Gibbs-Udriște-Dogaru nonholonomic hypersurface

We follow the ideas in [4]. Let D be an open subset in \mathbb{R}^5 and I a compact interval in \mathbb{R}^m , $m \in \{1, 2\}$. Consider the Pfaff equation $\omega = \omega_i(x) dx^i$, $i = \overline{1, 5}$, where $\omega_1 = 0$, $\omega_2 = -x^1$, $\omega_3 = 0$, $\omega_4 = x^3$, $\omega_5 = 1$.

We say that the integral manifold $r : I \rightarrow D$ of the Pfaff equation passes through the point $x_0 \in D$ if $\exists u_0 \in I$ such that $r(u_0) = x_0$. We observe that there is always an infinity of integral curves (the case $m = 1$) passing through x_0 . Because the Pfaff equation is not completely integrable, through x_0 there can pass integral manifolds of dimension 2 which have in common only the point x_0 . We denote by M_{x_0} the image of an integral manifold through x_0 and by Σ_{x_0} the family of all the images of integral manifolds through x_0 . The pair (Σ, D) , where we denoted $\Sigma = \{\Sigma_{x_0}\}_{x_0 \in D}$, is called *nonholonomic hypersurface on D attached to the Pfaff equation*.

We can attach to the Pfaff equation and to the point $x_0 \in D$, the tangent hyperplane

$$Q_{x_0} = \{x \in \mathbf{R}^5 \mid -x_0^1(x^2 - x_0^2) + x_0^3(x^4 - x_0^4) + x^5 - x_0^5 = 0\}.$$

Remark 4.1. *The correspondence $x_0 \rightarrow Q_{x_0} \subset T_{x_0}D$ defines a function Q on D which is a 4-dimensional distribution. A vector field Y belongs to the distribution Q if $Y(x_0) \in Q_{x_0}$, $\forall x_0 \in D$ or, equivalently $\omega(Y) = 0$ on D . Obviously, for every x_0 there exists a neighborhood U of x_0 and 4 vector fields Y_1, \dots, Y_4 of class C^1 on U such that $\{Y_1(x_0), \dots, Y_4(x_0)\}$ is a basis of H_{x_0} . The set $\{Y_1, \dots, Y_4\}$ is called local basis of distribution Q . The integral manifolds of Pfaff equation are called integral manifolds of the distribution Q .*

The distribution Q is not involutive (i.e. $Y, Z \in Q$ and Y, Z of class C^1 do not imply $[Y, Z] \in Q$) since the Pfaff equation is not completely integrable.

The quadratic form associated to the identity on Q_{x_0} , i.e., the real function $v \rightarrow (v, v)$, $v \in Q_{x_0}$ is called *the first fundamental form of the nonholonomic hypersurface (Σ, D) at the point x_0 and is denoted by g_{x_0}* . This function is a scalar product (the restriction to Q_{x_0} of the scalar product on \mathbb{R}^5). The function $x_0 \rightarrow g_{x_0}$, $x_0 \in D$ is called *the first fundamental form of (Σ, D)* . Taking into account the Pfaff equation, it appears the Riemannian metric

$$\begin{aligned} g &= \delta_{ij} dx^i dx^j \stackrel{ds^5=0}{=} \\ &= (dx^1)^2 + (1 + x^{1^2}) (dx^2)^2 + (dx^3)^2 + (1 + x^{3^2}) (dx^4)^2 - 2x^1 x^3 dx^2 dx^4. \end{aligned}$$

Let ξ be the unit vector field on D given by $\frac{1}{\|\omega\|}(\omega_1, \dots, \omega_5)$, where

$$\|\omega\| = \sqrt{\omega_1^2 + \dots + \omega_5^2}.$$

Let M_{x_0} be the image of a bidimensional integral manifold through x_0 , admitting the orthonormal vector fields ξ_1, ξ_2, ξ_3 . One of these fields coincides with the restriction of ξ to M_{x_0} if and only if $M_{x_0} \subset H_{x_0}$. If we put the condition $\sum_{i=1}^5 \omega_i^2(x) = 1$, then $\xi = (\omega_1, \dots, \omega_5)$. Let $v \in H_{x_0}$. By differentiating the identity $(\xi, \xi) = 1$ with respect to v we find $(D_v \xi, \xi)(x_0) = 0$ and hence $D_v \xi \in H_{x_0}$. The linear map

$$S_{x_0} : H_{x_0} \rightarrow H_{x_0}, \quad S_{x_0} = -D_v \xi$$

is called the *Weingarten map of (Σ, D) at x_0* . The geometric meaning of S_{x_0} can be deduced from the formula

$$D_v \xi = \left. \frac{d}{dt} \xi(\alpha(t)) \right|_{t=t_0},$$

where $\alpha : I \rightarrow D$ is an integral curve passing through x_0 at the moment t_0 with the velocity vector $\alpha'(t_0) = v$. Therefore S_{x_0} measures the rate of change of the direction of ξ while passing through x_0 along $\alpha(I)$. Since Q_{x_0} is identified to $\xi(\alpha(t_0))^\perp$, Q_{x_0} turns as the normal ξ turns and thus $S_{x_0}(v)$ can be interpreted as a measure of the turning of Q_{x_0} when passing through x_0 along $\alpha(I)$. Thus S_{x_0} contains information about the shape of (Σ, D) in x_0 .

The most important properties of Weingarten map of a nonholonomic hypersurface are included in the following two theorems ([4], [5]).

Theorem 4.1. *Let D be an open set in \mathbb{R}^n , $n \geq 3$ and the Pfaff equation*

$$\omega(x) = \sum_{i=1}^n \omega_i(x) dx^i = 0, \quad x = (x^1, \dots, x^n),$$

where $\omega_i : D \rightarrow \mathbb{R}$, $i = \overline{1, n}$ are C^1 functions. Let (Σ, D) be the nonholonomic hypersurface attached to the Pfaff equation, with $\sum_{i=1}^n \omega_i^2(x) = 1$. Let $x_0 \in D$ and $v \in H_{x_0}$. Then, for every integral curve $\alpha : I \rightarrow D$ with $\alpha(t_0) = x_0$, $\alpha'(t_0) = v$ the following relation holds

$$(\alpha''(t_0), \xi(x_0)) = (S_{x_0}(v), v).$$

Theorem 4.2. *The Weingarten map S_{x_0} is not self-adjoint, i.e., there exist $v, w \in Q_{x_0}$, such that*

$$(S_{x_0}(v), w) \neq (v, S_{x_0}(w)).$$

Let $S_{x_0}^* : Q_{x_0} \rightarrow Q_{x_0}$ be the adjoint of S_{x_0} , i.e., the linear map (uniquely) defined by $(S_{x_0}^*(v), w) = (v, S_{x_0}(w))$, $\forall v, w \in Q_{x_0}$. The matrix of $S_{x_0}^*$ with respect to an orthonormal basis of Q_{x_0} is the transpose of the matrix of S_{x_0} with respect to that basis. The linear map $\frac{1}{2}(S_{x_0} + S_{x_0}^*)$ is self-adjoint. The quadratic form associated to this map, i.e., the function

$$\Omega_{x_0} : Q_{x_0} \rightarrow \mathbf{R}, \quad \Omega_{x_0}(v) = \frac{1}{2} (S_{x_0}(v) + S_{x_0}^*(v), v),$$

is called the *second fundamental form of nonholonomic hypersurface (Σ, D) at x_0* .

We observe that $\Omega_{x_0}(v) = (\alpha''(t_0), \xi(x_0))$, where $\alpha : I \rightarrow D$ is an integral curve, with $\alpha(t_0) = x_0$ și $\alpha'(t_0) = v$. This quadratic form can be obtained by usual differentiation of the Pfaff form

$$-\sum_{i=1}^n \omega_i(x) dx^i \quad \left(\sum_{i=1}^n \omega_i^2(x) = 1 \right)$$

and then taking the symmetric part, i.e.

$$\Omega = -\frac{1}{2} \sum_{i,j=1}^n \left(\frac{\partial \omega_i}{\partial x^j} + \frac{\partial \omega_j}{\partial x^i} \right) (x) dx^i dx^j.$$

In general, the second fundamental form of (Σ, D) is given by

$$\Omega = -\frac{1}{2\|\omega\|} \sum_{i,j=1}^n \left(\frac{\partial\omega_i}{\partial x^j} + \frac{\partial\omega_j}{\partial x^i} \right) (x) dx^i dx^j.$$

The second fundamental form of the Pfaff nonholonomic hypersurface is (Σ, D) is

$$\Omega = \frac{1}{2\sqrt{1+x^2+x^3}} (dx^1 dx^2 - dx^3 dx^4).$$

Particularly, if $v \in Q_{x_0}$, $\|v\| = 1$, then $k(v) = \Omega_{x_0}(v)$ is called *the normal curvature of (Σ, D) at x_0 in the direction v* . The extrema of normal curvature are proper values of the linear map $\frac{1}{2}(S_{x_0} + S_{x_0}^*)$. This, being a self-adjoint linear map, admits real proper values $k_1(x_0), \dots, k_4(x_0)$ and orthonormal proper vectors e_1, \dots, e_4 , which constitute a basis in Q_{x_0} . The proper values $k_1(x_0), \dots, k_4(x_0)$ are called *principal curvatures of (Σ, D) at x_0* , and the proper vectors e_1, \dots, e_4 are called *principal directions*. If the principal curvatures are such ordered that $k_1(x_0) \leq k_2(x_0) \leq k_3(x_0) \leq k_4(x_0)$, then

$$\begin{aligned} k_4(x_0) &= \max_{\|v\|=1} k(v) \\ k_3(x_0) &= \max_{\|v\|=1, v \perp e_4} k(v) \\ k_2(x_0) &= \max_{\|v\|=1, v \perp \{e_3, e_4\}} k(v) \\ k_1(x_0) &= \min_{\|v\|=1} k(v). \end{aligned}$$

Since $v = \sum_{i=1}^4 (v, e_i) e_i = \sum_{i=1}^4 (\cos \theta) e_i$, we find the Euler formula

$$k(v) = \sum_{i=1}^4 k_i(x_0) \cos^2 \theta_i.$$

The number

$$K(v) = \det \frac{1}{2} c = k_1(x_0) k_2(x_0) k_3(x_0) k_4(x_0)$$

is called *the Gauss-Kronecker curvature of (Σ, D) at x_0* . The function $x_0 \rightarrow K(x_0)$, $x_0 \in D$ is called *Gauss-Kronecker curvature of (Σ, D)* .

The number

$$H(x_0) = \frac{1}{4} \operatorname{tr} \frac{1}{2} (S_{x_0} + S_{x_0}^*) = \frac{1}{4} \sum_{i=1}^4 k_i(x_0)$$

is called *the mean curvature of (Σ, D) at x_0* . The function $x_0 \rightarrow H(x_0)$, $x_0 \in D$ is called *the mean curvature of (Σ, D)* . The Gauss-Kronecker curvature and the mean curvature of Gibbs nonholonomic hypersurface (Σ, D) vanishes.

In this context, using the Christoffel symbol of second order, we calculate the Riemann tensor and finally we get the Ricci tensor

$$\begin{aligned}
 R_{11} &= -\frac{2+3x^3+x^4+x^1x^3}{2(1+x^1+x^3)^2}, \\
 R_{12} &= R_{21} = 0, \\
 R_{13} &= R_{31} = -\frac{x^1x^3(3+x^1+x^3)}{2(1+x^1+x^3)^2}, \\
 R_{14} &= R_{41} = 0, \\
 R_{22} &= \frac{-2+x^1-x^3+x^1x^3+x^4}{2(1+x^1+x^3)^2}, \\
 R_{23} &= R_{32} = 0, \\
 R_{24} &= R_{42} = -\frac{x^1x^3(2+x^1+x^3)}{2(1+x^1+x^3)^2}, \\
 R_{33} &= -\frac{2+3x^1+x^4+x^1x^3}{2(1+x^1+x^3)^2}, \\
 R_{34} &= R_{43} = 0, \\
 R_{44} &= \frac{-2-x^1+x^3+x^1x^3+x^4}{2(1+x^1+x^3)^2}.
 \end{aligned}$$

and the scalar curvature

$$c = \frac{-10 + 2x^1x^3 - x^1x^3 + x^3 - 2x^1 - 6x^3 - 8x^1 + x^3 + x^1x^3}{2(1+x^1+x^3)^2}.$$

5 Conclusions

The paper studies three different geometries of Gibbs nonholonomic hypersurface, namely: Vrănceanu geometry ([7], [6]), Udriște-Dogaru geometry ([4], [5]) and a third geometry introduced by the authors, combining Dobrescu's theory ([1]) with Udriște's theory ([5]). These include the first and second fundamental forms and their derived geometric objects.

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